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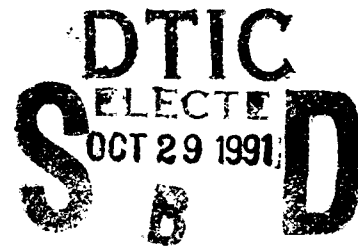
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**SIGNIFICANT DIGIT COMPUTATION  
OF THE ELLIPSOIDAL COVERAGE  
FUNCTION AND ITS INVERSE**

**BY ARMIDO R. DIDONATO  
STRATEGIC SYSTEMS DEPARTMENT**

**SEPTEMBER 1991**



Approved for public release; distribution is unlimited.



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# FOREWORD

The work described in this report was performed in the Space and Surface Systems Division with partial support from the Computer and Information Systems Division of the Strategic Systems Department. Its purpose was to develop a new algorithm for the ellipsoidal coverage function, and to design associated Fortran software which is suitable for inclusion in a high quality mathematics and/or statistics subroutine library.

This document was administratively reviewed by J. L. Sloop, Head, Space and Surface Systems Division. The flowchart on page 13 was prepared by Dottie J. Burgess on a Macintosh Iix personal computer.

Approved by:

*J. Ralph Fallin*  
J. Ralph Fallin, Acting Head  
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# I. INTRODUCTION

Three dimensional spherical coverage problems often appear in the study of weapon evaluations for aerial and submarine targets. Such studies require the capability to compute the ellipsoidal coverage function and its inverse. The ellipsoidal coverage function  $P(\bar{R}, \bar{H}, \bar{K}, \bar{L}, u, v, w)$  represents the probability of an event occurring in  $0x_1y_1z_1$ -space within a sphere SP with radius  $\bar{R}$  and center  $(\bar{H}, \bar{K}, \bar{L})$ , where

$$SP: (x_1 - \bar{H})^2 + (y_1 - \bar{K})^2 + (z_1 - \bar{L})^2 = \bar{R}^2.$$

The random event occurs under an uncorrelated trivariate normal distribution with mean  $(0,0,0)$  and standard deviations  $u, v, w$  in the  $x_1, y_1$ , and  $z_1$  directions, respectively. Thus

$$P(\bar{R}, \bar{H}, \bar{K}, \bar{L}, u, v, w) = \int \int \int_{\text{Volume of SP}} \mathfrak{F}(x_1, y_1, z_1, u, v, w) dx_1 dy_1 dz_1, \quad (1)$$

where

$$\mathfrak{F}(x_1, y_1, z_1, u, v, w) \equiv \frac{1}{(\sqrt{2\pi})^3 u v w} E[x_1/(\sqrt{2} u)] E[y_1/(\sqrt{2} v)] E[z_1/(\sqrt{2} w)], \quad E(z) \equiv e^{-z^2}, \quad (2)$$

and

$$P(\bar{R}, \bar{H}, \bar{K}, \bar{L}, u, v, w) = P(\bar{R}, \bar{K}, \bar{H}, \bar{L}, v, u, w) = P(\bar{R}, \bar{H}, \bar{L}, \bar{K}, u, w, v) = P(\bar{R}, |\bar{H}|, |\bar{K}|, |\bar{L}|, u, v, w). \quad (3)$$

Setting  $x_1 = \sqrt{2} u x$ ,  $y_1 = \sqrt{2} v y$ ,  $z_1 = \sqrt{2} w z$ , one obtains

$$P = \frac{1}{\pi \sqrt{\pi}} \int_{L-R}^{L+R} E(z) dz \int_{K-Y}^{K+Y} E(y) dy \int_{H-X}^{H+X} E(x) dx, \quad (4)$$

where

$$X = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w z)^2 - (\bar{K} - \sqrt{2} v y)^2} / (\sqrt{2} u), \quad Y = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w z)^2} / (\sqrt{2} v),$$

and

$$\begin{cases} H = \bar{H} / (\sqrt{2} u), & K = \bar{K} / (\sqrt{2} v), & L = \bar{L} / (\sqrt{2} w) \\ R_1 = \bar{R} / (\sqrt{2} u), & R_2 = \bar{R} / (\sqrt{2} v), & R_3 = \bar{R} / (\sqrt{2} w) = R. \end{cases} \quad (5)$$

It is easy to show, by using (4) with normalizations, that  $P$  is a function of six independent variables.

Rather than carry out the numerical triple integration of (4) directly we make use of an available computer program PKILL (or CIRCV) that yields the probability  $P_c(\bar{r}, \bar{H}, \bar{K}, u, v)$  of an event occurring under a bivariate normal distribution inside a circle in the  $0x_1y_1$ -plane, with center  $(\bar{H}, \bar{K})$  and radius  $\bar{r}$ .  $P_c$  is the two-dimensional analog of  $P$  [3, 4, 5, 6, 7].

Geometrically, one observes that  $P$  can be obtained by considering circular slices of SP parallel to the  $0xy$ -plane. For a fixed  $z$  in  $[L - R, L + R]$ , the  $xy$ -integration over a slice of radius  $\bar{r}$  yields  $\pi P_c$ .

Weighting  $P_c$  with  $E(z)/\sqrt{\pi}$  and integrating the result over  $z$  in  $[L - R, L + R]$ , gives  $P$ , i.e.,

$$P = \frac{1}{\sqrt{\pi}} \int_{L-R}^{L+R} E(z) P_c(\bar{r}, \bar{H}, \bar{K}, u, v) dz, \quad \bar{r} = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w z)^2}. \quad (6)$$

Another useful form for  $P$  can be obtained by splitting the integral in (6) into two pieces. One carries the integration from  $L - R$  to  $L$  and the other from  $L$  to  $L + R$ . For the second let  $z = 2L - t$ , then combining the results gives

$$P = \frac{1}{\sqrt{\pi}} \int_{L-R}^L [E(t) + E(2L - t)] P_c(\bar{r}, \bar{H}, \bar{K}, u, v) dt, \quad \bar{r} = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w t)^2}. \quad (7)$$

The symmetry properties of  $P$  indicated by (1) and (3) allow  $\bar{H}$ ,  $\bar{K}$ ,  $\bar{L}$  to be taken nonnegative. Since the integrand of  $P$  is positive and bounded, the order of integration in (1) is immaterial. Thus, as long as  $\bar{H}$  is associated with  $u$ ,  $\bar{K}$  with  $v$ , and  $\bar{L}$  with  $w$ , it does not matter which is called, say,  $\bar{L}$  and  $w$ . For example, if the order of integration is chosen so that the original  $x$ -integration is performed last, then if initially  $\bar{H} = 10$ ,  $u = 5$ ,  $\bar{L} = 20$ ,  $w = 7$ , we simply let  $\bar{H} = 20$ ,  $u = 7$ ,  $\bar{L} = 10$ ,  $w = 5$ . In this way, we can refer to (6) or (7) as the basic representations for  $P$ , where  $\bar{L}$  and  $w$  are always associated with the  $z$ -integration, with the understanding that the original order of integration may have been changed and the variables  $\bar{H}$ ,  $\bar{K}$ ,  $\bar{L}$ ,  $u$ ,  $v$ ,  $w$  renamed as above.

The objective in this report is to expand on the work described in [8]. In [8] for  $H^2 + K^2 + L^2 \leq 10^{10}$  and  $10^{-6} \leq P \leq .999999$ , procedures were given for computing  $P$  or its inverse  $\bar{R}$  (where  $P$  is given in place of  $\bar{R}$ ) to 6 decimal-digit accuracy. Here procedures are given for computing  $P$  or  $\bar{R}$  to 6 significant digits, when inherent error is negligible, for

$$H^2 + K^2 + L^2 \leq 1/\text{eps}, \quad 10^{-20} \leq P \leq .9999999, \quad (8)$$

where  $\text{eps}$  is the smallest positive machine dependent number such that  $1 + \text{eps} > 1$ . The double precision value of  $\text{eps}$  for the IBM PC is  $2^{-52} \simeq 2.22 \cdot 10^{-16}$ ; in single precision  $\text{eps} = 2^{-23} \simeq 1.19 \cdot 10^{-7}$ . Moreover, for the smaller ranges used in [8],  $P$  or  $\bar{R}$  can now be found to approximately 8 significant digits. All computations for testing were carried out in double precision PC Fortran on a Compaq Deskpro 386/20. The portable double precision Fortran function which yields  $P$ , given  $\bar{R}$ ,  $\bar{H}$ ,  $\bar{K}$ ,  $\bar{L}$ ,  $u$ ,  $v$ ,  $w$ , is called ELLCOV; the portable double precision subroutine which outputs  $\bar{R}$ , given  $P$ ,  $\bar{H}$ ,  $\bar{K}$ ,  $\bar{L}$ ,  $u$ ,  $v$ ,  $w$ , is called ELINV3. It is anticipated that the single precision version of these subprograms will be included in the Naval Surface Warfare Center (NAVSWC) Library of Mathematics Subroutines [13].

## II. COMPUTATION OF P

Initially in the computation of P by ELLCOV four tests are used to eliminate most cases where  $P \leq Z4 \equiv \max(10^{-50}, 100 \text{ epsm})$  or  $P \geq 1 - E_1$ , where epsm is the smallest machine dependent positive number the computer can use, and  $E_1 \equiv \max(10^{-11}, 50 \text{ eps})$ . In single precision for the IBM PC,  $\text{epsm} \simeq 1.17 \cdot 10^{-38}$ ; for double precision  $\text{epsm} \simeq 2.22 \cdot 10^{-308}$ .

Test #1 :

$$P \text{ set to } 0 \text{ if } \bar{R}^3 \leq 1.5\sqrt{2\pi} u v w Z4.$$

For Test #2, starting from (1) with

$$\bar{D} \equiv \sqrt{\bar{H}^2 + \bar{K}^2 + \bar{L}^2}, \quad M \equiv \max(u, v, w),$$

$$V = E[x_1/(\sqrt{2} u)] E[y_1/(\sqrt{2} v)] E[z_1/(\sqrt{2} w)],$$

we have, for  $\bar{D} \geq \bar{R}$ ,

$$V \leq E[x_1/(\sqrt{2} M)] E[y_1/(\sqrt{2} M)] E[z_1/(\sqrt{2} M)] \leq E[(\bar{D} - \bar{R})/(\sqrt{2} M)].$$

Hence,

$$P \leq \frac{1}{2\pi\sqrt{2\pi} u v w} E[(\bar{D} - \bar{R})/(\sqrt{2} M)] \frac{4}{3}\pi \bar{R}^3 \leq Z4.$$

Test #2 :

$$P \text{ set to } 0 \text{ if } \bar{R}^3 E(\gamma) \leq 1.5\sqrt{2\pi} u v w Z4$$

$$\gamma = (\bar{D} - \bar{R})/(M \sqrt{2}).$$

Test #3 :

$$P \text{ set to } 0 \text{ if } \mathcal{T} > 9.6$$

$$\mathcal{T} \equiv \max(H - R_1, K - R_2, L - R).$$

Test #4 :

$$P \text{ set to } 1 \text{ if } P^* \equiv P(\bar{R}, \bar{H}, \bar{K}, \bar{L}, M, M, M) \geq 1 - E_1$$

$$P^* \text{ is computed from (10) or (11).}$$

Generally, when none of the above tests are satisfied, P is computed by the numerical integration of (7). However, there are three situations where P can be evaluated without resorting to quadratures, and a fourth where P is given by  $P_C$ . We shall call these cases A, B, C, and D.

**CASE A:** For small  $\bar{R}$ 

The equivalent of (1) is to take the normal distribution with mean at  $(\bar{H}, \bar{K}, \bar{L})$  and to place the target sphere SP at the origin. Then using spherical coordinates

$$x_1 = \rho \cos \theta \sin \phi, \quad 0 \leq \rho \leq \bar{R}, \quad 0 \leq \theta \leq 2\pi, \quad 0 \leq \phi \leq \pi$$

$$y_1 = \rho \sin \theta \sin \phi$$

$$z_1 = \rho \cos \phi$$

with the volume element given by  $dV = \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$ , we obtain

$$P = \frac{1}{2\pi\sqrt{2\pi} \, u \, v \, w} \int_0^{\bar{R}} \int_0^{2\pi} \int_0^{\pi} E\left(\frac{\rho \cos \theta \sin \phi - \bar{H}}{\sqrt{2} \, u}\right) E\left(\frac{\rho \sin \theta \sin \phi - \bar{K}}{\sqrt{2} \, v}\right) E\left(\frac{\rho \cos \phi - \bar{L}}{\sqrt{2} \, w}\right) dV.$$

Expanding each of the exponentials about  $\rho = 0$  and carrying out the integrations gives, after some tedious algebra,

$$P \simeq \frac{4}{3\sqrt{\pi}} R_1 R_2 R_3 \left(1 + \frac{1}{10} T + E_r\right) e^{-(H^2 + K^2 + L^2)}, \quad (9)$$

where  $H, K, L$  and  $R_1, R_2, R$  are defined in (5) with

$$T = 2 \left[ R_1^2 (2H^2 - 1) + R_2^2 (2K^2 - 1) + R_3^2 (2L^2 - 1) \right]$$

$$E_r = \frac{1}{280} \left\{ T^2 - 8 \left[ R_1^4 (4H^2 - 1) + R_2^4 (4K^2 - 1) + R_3^4 (4L^2 - 1) \right] \right\}.$$

Then (9) is used to compute  $P$  when

$$\frac{1}{280} \left\{ T^2 + 8 \left| R_1^4 (4H^2 - 1) + R_2^4 (4K^2 - 1) + R_3^4 (4L^2 - 1) \right| \right\} \leq \max [5 \cdot 10^{-8}, \text{eps}].$$

Summarized results for cases B and C follow. The derivations of the final expressions either have been given in referenced papers or they will be given in the Appendix A of this report.

**CASE B:** For  $u = v = w$ 

$$P = \frac{1}{2} \text{aerf}(D, R) - \frac{2}{\sqrt{\pi}} R \left[ \frac{1 - e^{-4RD}}{4RD} \right] E(D - R), \quad D \equiv \sqrt{H^2 + K^2 + L^2} \neq 0 \quad (10)$$

$$P = \text{erf} R - \frac{2}{\sqrt{\pi}} R E(R), \quad D = 0, \quad (11)$$

where  $E(z)$  is defined in (2),  $R$  and  $L$  are defined in (5), and

$$\text{aerf}(D, R) \equiv \text{erf}(D + R) - \text{erf}(D - R), \quad \text{erf} x \equiv \frac{2}{\sqrt{\pi}} \int_0^x E(t) \, dt. \quad (12)$$

An algorithm is given in [9, App. A] which yields  $\text{aerf}$  to 13 significant digits. Equation(10) is derived in [8, App. A].



Subtraction of leading positive terms in (10) and (11) can result in loss of accuracy when computing P. Consider (11) for small R. Note that

$$\operatorname{erf} R = \frac{2}{\sqrt{\pi}} E(R) \sum_0 \frac{2^n}{1 \cdot 3 \cdots (2n+1)} R^{2n+1}, \quad [1, \text{p.297}]$$

so that the leading term cancels the 2nd term in (11). Therefore when  $R < .071$ , (11) is replaced by

$$P = \frac{2}{\sqrt{\pi}} E(R) \sum_1 \frac{2^n}{3 \cdots (2n+1)} R^{2n+1}, \quad D = 0. \quad (13)$$

In the case of (10) there are two situations where accuracy may be lost. First, consider  $D - R$  large and  $4RD > -\log \epsilon$  (For the IBM PC,  $\log \epsilon \simeq -36.044$ ). Then with

$$\operatorname{aerf}(D, R) = \operatorname{erfc}(D - R) - \operatorname{erfc}(D + R), \quad \operatorname{erfc} x = 1 - \operatorname{erf} x, \quad (14)$$

use

$$\operatorname{erfc} x \simeq \frac{E(x)}{\sqrt{\pi} x} \left[ 1 + \sum_1 (-1)^n \frac{1 \cdot 3 \cdots (2n-1)}{(2x^2)^n} \right], \quad (x \rightarrow \infty), \quad [1, \text{p.298}] \quad (15)$$

in(14). It is easy to see that the term  $\operatorname{erfc}(D + R)$  can be dropped since  $e^{-4RD}$  is negligible compared to one. Therefore (10) becomes

$$P \simeq \frac{E(D-R)}{2\sqrt{\pi}} \left[ \frac{1}{D-R} + \frac{1}{D-R} \sum_1 (-1)^n \frac{1 \cdot 3 \cdots (2n-1)}{[2(D-R)^2]^n} \right] - \frac{1}{2\sqrt{\pi} D} E(D-R),$$

or

$$P \simeq \frac{E(D-R)}{2\sqrt{\pi} (D-R)} \left[ \frac{R}{D} + \sum_1 (-1)^n \frac{1 \cdot 3 \cdots (2n-1)}{[2(D-R)^2]^n} \right], \quad D \neq 0. \quad (16)$$

The relation (16) for P is used when  $D - R > 4.25$ ,  $4RD > -\log \epsilon$ , and  $R > 0.425$ .

Loss of digits can also occur when R is small and  $D > 0$  in much the same way as was seen in obtaining (13). Here we use

$$P = \frac{4}{\sqrt{\pi}} E(D) \sum_1 \frac{n H_{2n-1}(D)/D}{(2n+1)!} R^{2n+1}, \quad (17)$$

where  $H_k(x)$  denotes the Hermite polynomial of degree k [1, p.771]. Equation (17) is used when  $R < .425$ . It is derived in Appendix A.

Subprogram ELLCOV calls subprogram EQSIG to evaluate P from the above relations when it recognizes Case B from its input.

CASE C: For  $u = v$  and  $\bar{H} = \bar{K} = 0$

Let

$$Z \equiv \sqrt{|1 - (w/u)^2|}, \quad S \equiv L - RZ^2, \quad F \equiv L + RZ^2.$$

Using the fact, which is easily shown, that

$$P_C(\bar{r}, 0, 0, u, u) = 1 - E(rw/u), \quad r = \sqrt{R^2 - (L - z)^2}, \quad [5, 6, 7] \quad (18)$$

and substituting this result into (6) gives separate relations for P when  $u > w$  and  $w > u$ :

$$\underline{u > w} \quad (i \equiv \sqrt{-1})$$

$$P = \frac{1}{2} \operatorname{erf}(L, R) - \frac{1}{2Z} \exp\left\{-\left(\frac{w}{u}\right)^2 [R^2 - (L/Z)^2]\right\} \operatorname{erf}\left(\frac{L}{Z}, RZ\right), \quad L \neq 0, \quad S \leq 0 \quad (19)$$

$$P = \frac{1}{2} \operatorname{erf}(L, R) - \frac{E(L - R)}{2Z} \left[ E\left(i\frac{S}{Z}\right) \operatorname{erfc}\left(\frac{S}{Z}\right) - e^{-4RL} E\left(i\frac{F}{Z}\right) \operatorname{erfc}\left(\frac{F}{Z}\right) \right], \quad L \neq 0, \quad S > 0 \quad (20)$$

$$P = \operatorname{erf} R - R E(Rw/u) \frac{\operatorname{erf}(RZ)}{RZ}, \quad L = 0. \quad (21)$$

$$\underline{w > u}$$

$$P = \frac{1}{2} \operatorname{erf}(L, R) - \frac{E(L - R)}{\sqrt{\pi} Z} \left[ \operatorname{daw}\left(\frac{F}{Z}\right) - e^{-4RL} \operatorname{daw}\left(\frac{S}{Z}\right) \right], \quad L \neq 0 \quad (22)$$

$$P = \operatorname{erf} R - \frac{2}{\sqrt{\pi}} R E(R) \frac{\operatorname{daw}(RZ)}{RZ}, \quad L = 0, \quad (23)$$

where

$$\operatorname{daw}(x) \equiv E(x) \int_0^x e^{t^2} dt \quad (\text{Dawson's integral}). \quad [1, \text{p.298}] \text{ and } [8] \quad (24)$$

Case C uses (19) – (23). They were derived in [8, pp. A4 – A7]. In a number of situations however these equations are written in different forms here to reduce the computational loss in accuracy. The modified forms appear below in (25) – (31) with their derivations given in Appendix A. In each of the modified relations given below the conditions under which they are used are specified first. The quantity P for case B is denoted here by  $P_B$ , and  $H_n(x)$  denotes the Hermite polynomial of degree n. These results are used in the subroutine SEQHZ3 which is called by ELLCOV when the latter has recognized case C from the input. A flowchart for SEQHZ3 is given at the end of this section.

$$\text{LET: } \{ 4RL \leq 10, \text{ and } R \leq \sqrt{2}, \text{ and } Rw/u \leq 1.$$

$$\begin{aligned} P &= \frac{2}{\sqrt{\pi}} R (Rw/u)^2 E(L/\sqrt{2}) \sum_1 F_{2n+1} \\ F_{2n+1} &= \frac{1}{2n+1} \left[ G_{2n-1} - 2 (Rw/u)^2 F_{2n-1} \right], \quad n \geq 1 \\ G_{2n-1} &= \frac{2R^{2n-2}}{(2n-1)(2n-2)!} E(L/\sqrt{2}) H_{2n-2}(L) \\ F_1 &= 0, \quad H_0 = 1, \quad G_1 = 2 E(L/\sqrt{2}). \end{aligned} \quad (25)$$

$$\text{LET: } \begin{cases} R > \sqrt{2}, \text{ or } Rw/u > 1, \text{ and} \\ L = 0 \text{ and } RZ \leq \sqrt{3}. \end{cases}$$

$$P = P_B - \frac{2R}{\sqrt{\pi}} E(R) \sum_1 \frac{2^n}{3 \dots (2n+1)} (RZ)^{2n}, \quad u \geq w \quad (26)$$

$$P = P_B - \frac{2R}{\sqrt{\pi}} E(R) \sum_1 \frac{(-2)^n}{1 \cdot 3 \dots (2n+1)} (RZ)^{2n}, \quad w \geq u. \quad (27)$$

$$\text{LET: } \begin{cases} 4RL > 10 \text{ or } R > \sqrt{2} \text{ or } Rw/u > 1, \text{ and} \\ L \neq 0 \text{ or } RZ > \sqrt{3}, \text{ and} \\ w/u > 1/10 \text{ or } (w/u)^2 \max(R, L) > 1/2. \end{cases}$$

Let

$$\text{erfcr}(x) \equiv 1/\sqrt{\pi} - x e^{x^2} \text{erfc } x, \quad x \geq 4$$

$$\text{efsz} \equiv F \text{erfcr}(S/Z) - S E(2\sqrt{RL}) \text{erfcr}(F/Z).$$

Then

$$P = P_B - \frac{E(R-L)}{2FS} \left\{ \frac{RZ^2}{\sqrt{\pi}} \left[ 4R^2Z^2 \frac{[1 - E(2\sqrt{RL})]}{4RL} + (1 + E(2\sqrt{RL})) \right] - \text{efsz} \right\}, \quad u > w, \quad \frac{S}{Z} \geq 5, \quad (28)$$

and

$$P = P_B - \frac{E(R-L)Z^2}{2\sqrt{\pi}FS} \left\{ 4R^3Z^2 \frac{[1 - E(2\sqrt{RL})]}{4RL} - R[1 + E(2\sqrt{RL})] + \text{bdaw1} \right\}, \quad w > u, \quad \frac{S}{Z} \geq 5, \quad (29)$$

where

$$\text{daw}(y) \simeq 1/(2y) [1 + \text{Frac}(y)/y^2], \quad y \geq 5 \quad [2]$$

$$\text{bdaw1} = S/F^2 \text{Frac}(F/Z) - F/S^2 E(2\sqrt{RL}) \text{Frac}(S/Z).$$

The computation of  $\text{erfcr}(x)$  is carried out by the Fortran function  $\text{ERFCR}$  given in [13]. The evaluation of  $\text{daw}(x)$  is based on minimax rational approximations [2]. For  $t \geq 5$ , the quantity  $\text{Frac}(t)$  represents a rational function in  $1/t^2$ . The function  $\text{bdaw1}$  is computed by the Fortran subroutine  $\text{BDAW1}$  given in Appendix B.

$$\text{LET: } \begin{cases} 4RL > 10 \text{ or } R > \sqrt{2} \text{ or } Rw/u > 1, \text{ and} \\ L = 0 \text{ or } RZ > \sqrt{3}, \text{ and} \\ w/u > 1/10 \text{ or } (w/u)^2 \max(R, L) > 1/2. \end{cases}$$

Let

$$\text{dxdaw}(x) \equiv \text{daw}(x)/x.$$

Then

$$P = 1/2 \text{aerf}(L, R) - (2/\sqrt{\pi}) RE(L-R) \text{dxdaw}(RZ), \quad w > u, \quad L = 0, \quad \frac{S}{Z} < 5, \quad (30)$$

where  $\text{dxdaw}(x)$  is computed by the Fortran function  $\text{DXDAW}$  which is given in Appendix B.

$$\text{LET: } \left\{ \begin{array}{l} 4RL > 10 \text{ or } R > \sqrt{2} \text{ or } R w/u > 1, \text{ and} \\ L \neq 0 \text{ or } R Z > \sqrt{3}, \text{ and} \\ w/u \leq 1/10 \text{ or } (w/u)^2 \max(R, L) \leq 1/2. \end{array} \right.$$

With  $i = \sqrt{-1}$ ,

$$P = \frac{1}{2} \left\{ \left( 1 - e^{-(w/u)^2 [R^2 - L^2]} \right) \text{erf}(L, R) - e^{-(w/u)^2 [R^2 - L^2]} \sum_1 \frac{H_n(-i L w/u)}{n!} \frac{2}{\sqrt{\pi}} \int_{L-R}^{L+R} E(t) \left( \frac{-i w}{u} \right)^n t^n dt \right\}. \quad (31)$$

The recurrence relations used to generate (31) in SEQHZ3 are given in Appendix A.

CASE D:

$$\text{For } L - R < -6 \text{ and } \bar{r} = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w t)^2} \sim \bar{R}$$

$$P = P_c(\bar{R}, \bar{H}, \bar{K}, u, v). \quad (32)$$

This case is recognized when

$$(\bar{L} - \sqrt{2} w A)^2 \leq \bar{R}^2 \min(\text{eps}/3, 10^{-12}), \quad (33)$$

where A replaces the lower limit of integration in (7). For example, let  $\bar{R} = 10^{10}$ ,  $u = 10^{10}$ ,  $v = 2$ ,  $w = 1$ ,  $\bar{H} = 10^{10}$ ,  $\bar{K} = 1$ ,  $\bar{L} = 2$ . In this case  $L - R = (2 - 10^{10})/\sqrt{2}$  can safely be replaced by  $A = -7.0$  since  $\bar{r}$  in (7) is an increasing function of t. Then

$$(\bar{L} - \sqrt{2} w A)^2 / \bar{R}^2 \simeq 12 \cdot 10^{-20} < (2.22/3) \cdot 10^{-16}, \text{ and } \text{erf}(7.0) \simeq 1 - 4 \cdot 10^{-23}.$$

Hence  $P = P_c(\bar{R}, \bar{H}, \bar{K}, u, v) = .47724 \ 986805$ .

In general, excluding cases A,B,C,D, the probability P is computed from (7) by numerical integration. A 24th order Gaussian quadrature rule [1, p.916] is used for this purpose. The primary objectives are: (a) to determine the order of integration, i.e., which integration should be carried out last as the t-integration in (7), (b) to obtain effective limits of integration.

From Test#3,  $\mathcal{T} \leq 9.60$ . Indeed, if  $L - R > 9.6$ , then

$$P \leq \frac{1}{\sqrt{\pi}} \int_{9.6}^{\infty} E(z) P_c(\bar{r}, \bar{H}, \bar{K}, u, v) dz \leq \frac{1}{\sqrt{\pi}} \int_{9.6}^{\infty} E(z) dz = \frac{1}{2} \text{erfc}(9.6) \simeq 2.8 \cdot 10^{-42}.$$

In addition, the lower limit in (6) or (7) can be restricted to values greater than  $-7.0$ . In fact, by Test#4 and (10), when  $\bar{R} > \bar{D}$ , then  $P \geq P^* \simeq \text{erf}(D, R)/2$  where the second term in (10) can be neglected for  $\bar{R} - \bar{D} > 7\sqrt{2} M$ . Therefore since P is no less than  $P^*$ ,

$$P > \text{erf}(D, R)/2 \geq \text{erf}(7.0) \simeq 1 - 4 \cdot 10^{-23}.$$

Consequently, if we identify an initial effective integration range in (7) to be from A to B, then

$$A \equiv \max(L - R, -7.0), \quad B \equiv \min(L, 9.6). \quad (34)$$

It is understood that an A and B are determined for the three different integration orders, i.e., with the original x,y, and the z-integrations reordered so that each is carried out last.

Let the integrand of (7) be denoted by  $G(t)$ . Then ELLCOV calls TQUA1 to determine whether A can be raised and/or B lowered from the initial values given in (34). At each Gaussian abscissa  $t_i$  on  $[A,B]$  the integrand of (7),  $G(t_i)$ , is evaluated at increasing  $i$  starting at  $i = 1$ , where  $A = t_0 < t_1 < \dots < t_{23} < t_{24} < t_{25} = B$ . Set the quantity  $T8 = \max(100 \text{ epsm}, 10^{-42})$ , with epsm as defined on page 3. Then for the smallest  $t_i$  for which  $G(t_i) > T8$ , A is replaced by  $t_{i-1}$ . Similarly, starting at  $j = 24$  and with decreasing  $j$ , the largest  $t_j$  for which  $G(t_j) > T8$  is found. B is then replaced by  $t_{j+1}$ . The function  $G(t)$  is computed by the Fortran function FN2 given in Appendix B.

At this point three sets of integration limits A and B have been determined, one for each different last integration. Indicate these limits by AX, BX; AY, BY; AZ, BZ. The final order of integration is now selected as the one for which the integration interval  $(B - A)$  is the largest. An exception to this choice is made if one lower limit of integration is  $< -2$  and the other two lower limits are not negative, for example,  $AX \leq -2$  and AY and AZ are not negative. In this particular case the x integration is chosen as the last integration. If the above exception does not hold and a tie occurs, say between the x and y integrations,  $(BX - AX = BY - AY)$  the x-integration is carried out last if  $AX > AY$  and  $AX < -2$ , otherwise the y-integration is carried out last. Choosing the order of integration in the ways described above is based on numerical studies and the heuristic argument that the more spike-like the integrand the more difficult it is to obtain an accurate numerical integration.

With the appropriate interchanges having been made, the integration to be carried out last has now been set and it is indicated by the z or t-integration as shown in (6) or (7). Two further attempts are subsequently made to improve the values of A and B.

It may occur that for some  $\bar{t}$  in  $[A,B]$ ,  $P_c \simeq 1 - \epsilon$ ,  $\epsilon = 2.3 \cdot 10^{-11}$ , in which case, since  $\bar{r}$  in (7) is an increasing function of  $t$ ,

$$P \simeq \frac{1}{\sqrt{\pi}} \int_A^{\bar{t}} [E(t) + E(2L - t)] P_c(\bar{r}, \bar{H}, \bar{K}, u, v) dt + \frac{1}{2} \text{erf}(L, \mathcal{V}),$$

where  $\mathcal{V}$  is defined below. Such a situation is recognized by employing previous results from [3, p.15] and [4,7]. We have  $P_c > 1 - 2.3 \cdot 10^{-11}$ , for  $t \geq \bar{t}$ , if

$$\bar{r} = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w t)^2} \geq \sqrt{\bar{H}^2 + \bar{K}^2} + 7 m \equiv G, \quad m \equiv \max(u, v),$$

or

$$|\bar{L} - \sqrt{2} w t| \leq \sqrt{\bar{R}^2 - G^2} \equiv \bar{V},$$

or

$$\bar{t} = L - \bar{V} \leq t \leq L + \bar{V}, \quad \bar{V} \equiv \bar{V}/(\sqrt{2} w).$$

At this point a final effort is made to improve A and B. ELLCOV calls subroutine SQUAD which first evaluates the integrand in (7),  $G(t)$ , at each Gaussian abscissa on  $[A, B]$  starting from the endpoints and moving symmetrically toward the center of  $[A, B]$ . An estimate is now available for P. With this estimate, the same procedure used in TQUA1 is carried out by SQUAD to possibly further improve A and/or B. The difference here is that the better estimate for P replaces T8 used in TQUA1. If however both A and B are unchanged by SQUAD then the value for P obtained from SQUAD gives the final result for P.

If A and/or B are improved by SQUAD, then ELLCOV calls subroutine RQUAD to obtain P by a final 24th order Gaussian numerical integration, based on the latest values of A and B found from SQUAD. In SQUAD or RQUAD, we have

$$P = \frac{1}{\sqrt{\pi}} \frac{B-A}{2} \sum_{i=1}^{24} y(i) [G(t_i^-) + G(t_i^+)],$$

where

$$G(t) = [E(t) + E(2L - t)] P_c[\bar{r}(t), \bar{H}, \bar{K}, u, v]$$

$$\bar{r}(t) = \sqrt{\bar{R}^2 - (\bar{L} - \sqrt{2} w t)^2}$$

$$t_i^- = \frac{B+A}{2} - x(i) \frac{B-A}{2}$$

$$t_i^+ = \frac{B+A}{2} + x(i) \frac{B-A}{2}.$$

$$y(i) = 24\text{th order Gaussian weights on } [-1, 1]$$

$$x(i) = 24\text{th order Gaussian abscissae on } [-1, 1]. \quad [1, \text{ p. 916}]$$

The  $x(i)$  and  $y(i)$  are stored in ELLCOV (see listing in Appendix B).

A parameter J is set in ELLCOV to either 0 or 1 or 2. It is set to 0 if, referring to  $P_c$  above,  $\bar{H} = \bar{K} = 0$ ; it is set to 1 if  $u = v$ . In either of these two cases the subroutine CIRCv is used to evaluate  $P_c$ , otherwise the subroutine PKILL is used for this purpose with J set to 2. It is advantageous to use CIRCv if possible since it evaluates  $P_c$  more accurately than PKILL and is about ten times faster. However the order of the integration is determined, as described above, by TQUA1 and no effort is made to modify that choice.

The quantity  $\bar{r}(t_i)$  can be simplified when  $A = L - R$  and  $\bar{L} = L$ . In this case, it is easy to show that

$$\begin{cases} \bar{r}(t_i^-) = \bar{R} U(i) = \bar{R} \sqrt{1 - [1 + x(i)]^2/4}, & i = 12, 11, \dots, 2, 1 \\ \bar{r}(t_i^+) = \bar{R} U(12 + i) = \bar{R} \sqrt{1 - [1 - x(i)]^2/4}, & i = 12, 11, \dots, 2, 1. \end{cases}$$

The array  $U(j)$  has been precomputed and is available, thus eliminating the computation of 24 square roots and a possible loss of accuracy. When this feature comes into play, the parameter IL in SQUAD is set to 1. The array is stored in FN2 where  $G(t)$  is computed, (See the listing in Appendix B).

Although we claim 6 significant-digit accuracy for  $P$ , it may not be possible to obtain this accuracy for extreme values of the input where inherent error plays a dominant role. For example, using ELLCOV on an IBM PC with double precision Fortran ( $\sim 16$  significant digits), let

$$\bar{H} = 10^{13}, \quad \bar{K} = 0, \quad \bar{L} = 0, \quad u = 5, \quad v = w = 1,$$

then

$\bar{R}$	$P$
1.0000 00000 0026 $\cdot 10^{13}$	.99999 <u>99004</u>
1.0000 00000 0025 $\cdot 10^{13}$	.99999 <u>97136</u>
1.0000 00000 0000 $\cdot 10^{13}$	.50000 00000
9.9999 99999 9999 $\cdot 10^{12}$	.49214 <u>92357</u>
9.9999 99999 9600 $\cdot 10^{12}$	.62292 <u>51932</u> $\cdot 10^{-15}$
9.9999 99999 9599 $\cdot 10^{12}$	.52932 <u>23990</u> $\cdot 10^{-15}$ .

The underlined digits are in doubt.

A few more numerical results are included where inherent error is not a factor. If

$$\bar{H} = 1.0, \quad \bar{K} = 2.0, \quad \bar{L} = 3.0, \quad u = 2, \quad v = 4, \quad w = 1,$$

then

$\bar{R}$	$P$
1.0000 00000 0000 $\cdot 10^{-2}$	.28764 95875 $\cdot 10^{-9}$
5.0000 00000 0000 $\cdot 10^{-1}$	.43140 77476 $\cdot 10^{-4}$
1.0000 00000 0000	.53583 15121 $\cdot 10^{-3}$
3.0000 00000 0000	.79694 49445 $\cdot 10^{-1}$
4.0000 00000 0000	.25115 76137
5.0000 00000 0000	.47295 03432
7.0000 00000 0000	.78979 21674
1.2000 00000 0000 $\cdot 10^1$	.98945 55844
1.8000 00000 0000 $\cdot 10^1$	.99994 81467 .

We also take the opportunity here to correct 3 typographical errors in Table 1 of [8, p.12].

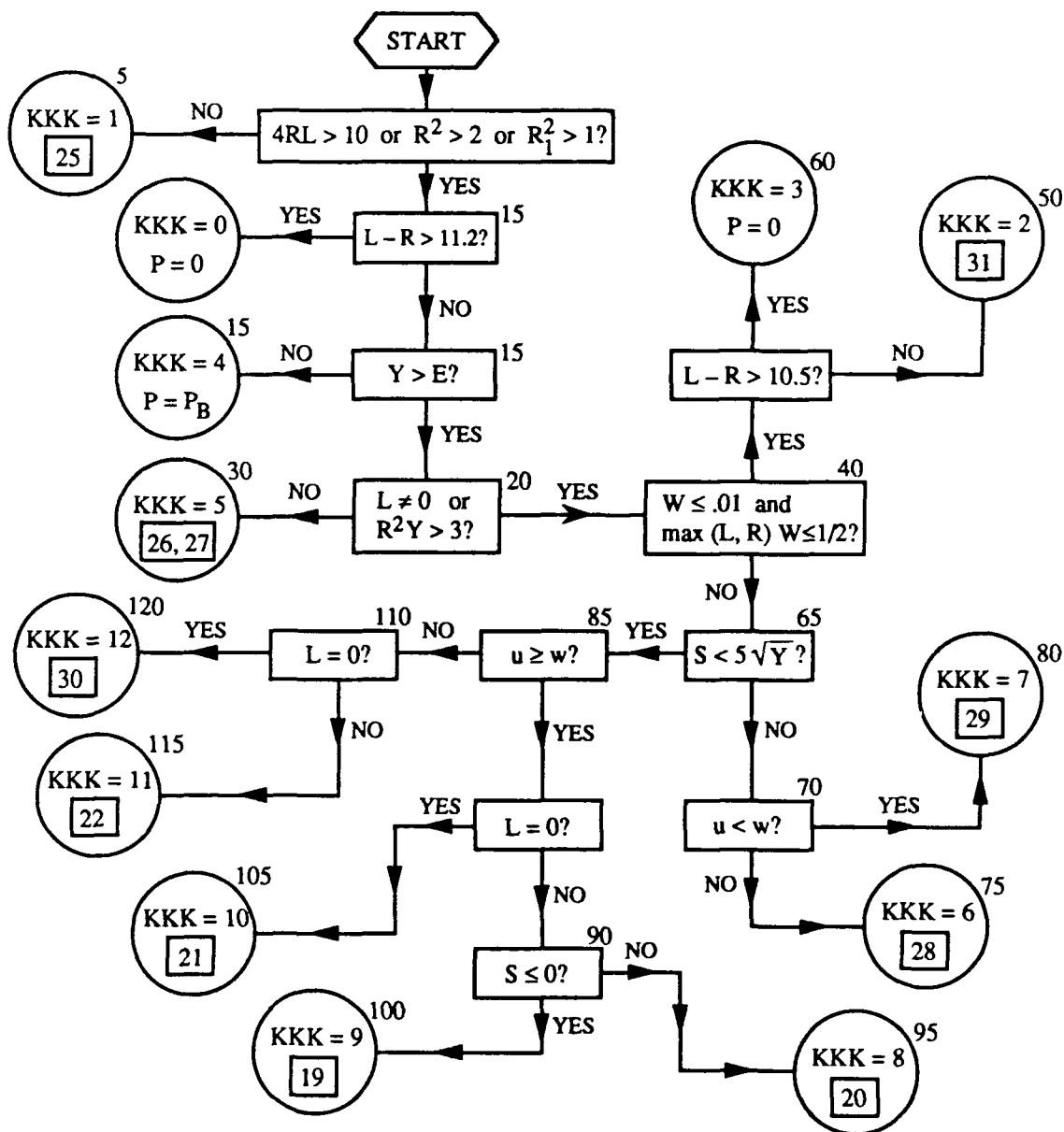
$$\begin{array}{llllll} \bar{R} = 1 & \bar{H} = 1/2 & \bar{K} = \bar{L} = 0 & u = v = w = 1 & P = .17955\ 97978 \\ \bar{R} = 1 & \bar{H} = 2 & \bar{K} = \bar{L} = 0 & u = v = w = \sqrt{2/3} & P = .33473\ 93607 \cdot 10^{-1} \\ \bar{R} = 1 & \bar{H} = 0 & \bar{K} = \bar{L} = 0 & u = 2v = 2w = 2/\sqrt{3} & P = .37539\ 30077 \end{array}$$

Extensive testing was carried out to establish the accuracy claimed above for the computation of  $P$  by ELLCOV. This testing, using a Compaq Deskpro 386/20 PC, compared ELLCOV double precision results, with the results from an adaptive quadrature subroutine, DQAGS, which is contained in NSWCLIB [13].



## FLOWCHART FOR SEQHZ3

CASE C:  $H = K = 0$ ,  $u = v \neq w$ ,  $W \equiv (w/u)^2$ ,  $Y \equiv |1 - W|$ ,  $S \equiv L - RY$



•  $P_B \equiv P$  for  $u = v = w$ .

•  $E \equiv \max(\text{eps} / 2, 10^{-10})$  See page 2 for eps.

• KKK: integer used to identify a particular branch of SEQHZ3.

• Numbers in rectangles refer to equation numbers of the text.

• Numbers outside boxes and circles refer to Fortran labels of the source code.

### III. COMPUTATION OF $\bar{R}$ (The inverse problem)

In this section a procedure is described, given  $P, \bar{H}, \bar{K}, \bar{L}, u, v, w$ , to estimate  $\bar{R}$ . The method for estimating  $\bar{R}$  within a given accuracy generally requires a sequence of values of  $P$  from ELLCOV. Since these computations usually involve time-consuming numerical triple integrations an effort is made to keep them to a minimum by obtaining a good early estimate of  $\bar{R}$ . Once such an estimate is found, halving, regula-falsi, and King's root finding procedure [12] are used to obtain a final estimate,  $\tilde{R}$ , for  $\bar{R}$ . The objective is to obtain  $\tilde{R}$  to at least six significant digits (when inherent error does not contaminate the computations) for the range specified earlier in (8), namely

$$H^2 + K^2 + L^2 \leq 1/\text{eps}, \quad 10^{-20} \leq P \leq .9999999. \quad (35)$$

The Fortran subroutine ELINV3 yields  $\tilde{R}$ . A listing of the code is given in Appendix C with listings for three additional portable supporting subprograms ELLRC, FCN1, SUB3.

The unknown value of  $\bar{R}$  will always be contained in a known interval  $[R_L, R_H]$ . Initial values of the lower and upper bounds,  $R_L$  and  $R_H$ , are found for  $\bar{R}$ .

Let  $I \equiv \max [3\sqrt{\pi/2} Puvw, (\sqrt{\pi/2} P M)^3]$ ,  $M \equiv \max(u,v,w)$ . Then

$$\bar{R} \geq R_L = \begin{cases} \bar{D}, & \text{if } P > 1/2 \text{ and } I \leq \bar{D}^3, \\ I^{1/3}, & \text{otherwise.} \end{cases} \quad \bar{D} \equiv \sqrt{H^2 + K^2 + L^2} \quad (36)$$

The derivation of (36) is discussed in [8]. An initial value of  $R_H$  is obtained from the relation

$$\bar{R} \leq R_H = \bar{D} + B(j)M \quad \text{with} \quad A(j) = P(B(j)M, 0, 0, 0, M, M, M),$$

where  $B(j)M$  gives the radius of a sphere centered at the origin such that  $A(j)$  is the smallest value for which  $A(j) > P$ . This approximation is discussed more fully in [8; pp. 14-15]. The arrays  $A(k)$  and  $B(k)$  are given by

$A(1) = 10^{-30}$	$B(1) = 1.56 \cdot 10^{-10}$
$A(2) = 10^{-25}$	$B(2) = 7.23 \cdot 10^{-9}$
$A(3) = 10^{-20}$	$B(3) = 3.36 \cdot 10^{-7}$
$A(4) = 10^{-15}$	$B(4) = 1.56 \cdot 10^{-5}$
$A(5) = 10^{-10}$	$B(5) = 7.22 \cdot 10^{-4}$
$A(6) = 10^{-8}$	$B(6) = 3.36 \cdot 10^{-3}$
$A(7) = 5 \cdot 10^{-6}$	$B(7) = 2.66 \cdot 10^{-2}$
$A(8) = 10^{-4}$	$B(8) = 7.23 \cdot 10^{-2}$
$A(9) = 10^{-2}$	$B(9) = 0.339$
$A(10) = 0.10$	$B(10) = 0.765$
$A(11) = 0.30$	$B(11) = 1.1933$
$A(12) = 0.60$	$B(12) = 1.7170$
$A(13) = 0.90$	$B(13) = 2.5005$
$A(14) = 0.999$	$B(14) = 4.0335$
$A(15) = 0.999999$	$B(15) = 5.5380$
$A(16) = 0.99999999$	$B(16) = 6.3500$
$A(17) = 1.00$	$B(17) = 7.7000$

An improvement for  $\bar{R}$  is generally obtained by using an estimate  $R_G$  given by F.E. Grubbs [11]. His estimate depends on the percentage point of the Chi-squared distribution which is determined by using the subroutine GAMINV contained in the NAVSWC math library [13]. The quantity actually given by Grubbs is  $R_G^2$ , namely

$$R_G^2 = \sigma^2 \{ [X(4/V_5, P) - 4/V_5] W_2 + Z \}, \quad (37)$$

where

$$\sigma^2 \equiv u^2 + v^2 + w^2$$

$$Z \equiv 1 + \bar{D}^2 / \sigma^2, \quad \bar{D}^2 \equiv \bar{H}^2 + \bar{K}^2 + \bar{L}^2$$

$$V_4 \equiv 2 \left\{ \frac{u^4}{\sigma^4} [1 + 4H^2] + \frac{v^4}{\sigma^4} [1 + 4K^2] + \frac{w^4}{\sigma^4} [1 + 4L^2] \right\}$$

$$T_5 \equiv 8 \left\{ \frac{u^6}{\sigma^6} [1 + 6H^2] + \frac{v^6}{\sigma^6} [1 + 6K^2] + \frac{w^6}{\sigma^6} [1 + 6L^2] \right\}$$

$$W_2 \equiv T_5 / (2V_4), \quad V_5 \equiv T_5^2 / V_4^3,$$

and  $X(A, P)$  satisfies the incomplete gamma function relation

$$P = \frac{1}{\Gamma(\alpha)} \int_0^X (\alpha, P) e^{-t} t^{\alpha-1} dt, \quad \alpha \equiv 4/V_5. \quad [1, p.255]$$

The quantity  $R_G^2$  from (37) occasionally may give a poor estimate for  $\bar{R}^2$  or it may even give a negative value and consequently be of no use in such cases.

We attempt to improve our initial estimate for  $\bar{R}$  by finding a constant  $\bar{R}_C$ , where

$$P = \int_{\bar{L} - \bar{R}_C}^{\bar{L} + \bar{R}_C} \int_{\bar{K} - \bar{R}_C}^{\bar{K} + \bar{R}_C} \int_{\bar{H} - \bar{R}_C}^{\bar{H} + \bar{R}_C} \mathfrak{F}(x_1, y_1, z_1, u, v, w) dx_1 dy_1 dz_1. \quad (38)$$

The quantity  $\mathfrak{F}$  is defined in (2). The right hand side of (38) gives the cumulative normal probability  $P$  over the cube, with center at  $(\bar{H}, \bar{K}, \bar{L})$  and equal sides parallel to the  $x_1$ ,  $y_1$ , and  $z_1$  axes, which contains the sphere with the same center, and of radius  $\bar{R}_C$ . The subroutine ELLRC, using Newton-Raphson, gives  $\bar{R}_C$ . Hence  $\bar{R}_C < \bar{R} < \sqrt{3} \bar{R}_C$ . The maximum number of Newton-Raphson iterations allowed by ELLRC is 40. The Fortran listing for ELLRC is given in Appendix C.

With the latest values for  $R_L$  and  $R_H$  and the corresponding  $P$  values  $P_L$  and  $P_H$ , a halving procedure is carried out until  $P_L > 10^{-3} P_H$  and  $(R_H - R_L) \leq \bar{R}/10$ . When both of the above inequalities are satisfied ELINV3 proceeds to obtain a final estimate for  $\bar{R}$  by employing King's method [8, 12]. The method was described with a flow chart in [8]. It may be looked upon as a modified regula-falsi procedure. An estimate  $\tilde{R}$  for  $\bar{R}$  is considered satisfactory if  $|P(\tilde{R}) - P| \leq E8$ , where  $E8$  depends on  $P$  and is given by

$$E8 = \begin{cases} \max(10 \text{ eps}, 10^{-8}) P & 0 < P < .999 \\ \max(10 \text{ eps}, 10^{-9}) & .999 \leq P < .999999 \\ \max(10 \text{ eps}, 10^{-10}) & .999999 \leq P < .99999999 \\ \max(10 \text{ eps}, 10^{-11}) & .99999999 \leq P < 1.0. \end{cases} \quad (\text{See page 2 for eps}).$$

If the above inequality  $|P(\tilde{R}) - P| \leq E8$  is satisfied an indicator IND is set to 0 in ELINV3. Other exits from ELINV3 are also identified by IND, namely,

$$\begin{aligned} \text{IND} &= -1 & P < \max(10^{-40}, 10^6 \text{ epsm}) & \quad (\text{See page 3 for epsm}). \\ \text{IND} &= +1 & P > 1 - \max(10^{-12}, 10 \text{ eps}) \\ \text{IND} &= +2 & N \geq 30 \\ \text{IND} &= +3 & R_H - R_L < \max(10 \text{ eps}, 10^{-14}) \tilde{R} \\ \text{IND} &= +4 & \text{ELLCOV not able to yield } P(\tilde{R}) \text{ with the accuracy required.} \end{aligned}$$

If  $\text{IND} = |1|$ ,  $P$  has been specified outside allowable limits. The output  $\tilde{R}$  is set to  $-10^{10}$ . Let  $N$  denote the number of iterations. If  $\text{IND} = 2$ , then the maximum allowable number of iterations (30) for finding  $\tilde{R}$  was reached.  $N$  is increased by one for each call to ELLCOV for which its output is nonzero. Extensive checking has found  $N \leq 27$ . If  $\text{IND} = 3$ , then more digits are required in the  $\tilde{R}$  estimates than are available, i.e, the word length for the particular machine in use is too short. If  $\text{IND} = 4$ , then the subprogram that yields  $P(\tilde{R})$ , ELLCOV, cannot produce the accuracy required. This difficulty can only appear if  $P$  is very near one and it is due to either the limitations of the numerical integration or to inherent error.

Some numerical results from ELINV3 are given below in Table 1 (4 parts) which reproduces Table 2 of [8] with improved estimates for  $\bar{R}$ . The notation for Table 1 follows. Let  $\bar{P}$  denote the input values of  $P$  and let  $\tilde{R}$  denote the final estimate for  $\bar{R}$  using ELINV3. RERR represents the relative error given by  $|P(\tilde{R}) - \bar{P}| / \bar{P}$ . IND and  $N$  have been defined above.

TABLE 1 (PART 1)

$u = 2.0$	$v = 4.0$	$w = 6.0$
$\bar{H} = 5.00$	$\bar{K} = 10.0$	$\bar{L} = 20.0$
$\tilde{R}$	RERR	IND N $\bar{P}$
$0.3183274539 \cdot 10^1$	$+0.260 \cdot 10^{-8}$	0 8 $0.500000 \cdot 10^{-5}$
$0.1028906156 \cdot 10^2$	$-0.392 \cdot 10^{-13}$	0 8 $0.500000 \cdot 10^{-2}$
$0.1660907596 \cdot 10^2$	$-0.641 \cdot 10^{-12}$	0 6 0.100000
$0.2339931591 \cdot 10^2$	$+0.163 \cdot 10^{-9}$	0 5 0.500000
$0.3048621773 \cdot 10^2$	$+0.708 \cdot 10^{-8}$	0 7 0.900000
$0.4077123752 \cdot 10^2$	$-0.231 \cdot 10^{-10}$	0 7 0.999000
$0.4844201564 \cdot 10^2$	$+0.956 \cdot 10^{-10}$	0 6 0.999995

TABLE 1 (PART 2)

$u = 5.0 \cdot 10^{-5}$	$v = 5.0 \cdot 10^{-2}$	$w = 1.0$
$\bar{H} = 0.20$	$\bar{K} = 1.00$	$\bar{L} = 5.00$
$\tilde{R}$	RERR	IND N $\bar{P}$
$0.1171110995 \cdot 10^1$	$+0.653 \cdot 10^{-9}$	0 9 $0.500000 \cdot 10^{-5}$
$0.2629994892 \cdot 10^1$	$-0.127 \cdot 10^{-12}$	0 8 $0.500000 \cdot 10^{-2}$
$0.3855992354 \cdot 10^1$	$-0.143 \cdot 10^{-11}$	0 6 0.100000
$0.5103195068 \cdot 10^1$	$+0.287 \cdot 10^{-12}$	0 7 0.500000
$0.6364036803 \cdot 10^1$	$+0.572 \cdot 10^{-8}$	0 7 0.900000
$0.8154468511 \cdot 10^1$	$-0.259 \cdot 10^{-10}$	0 7 0.999000
$0.9472449895 \cdot 10^1$	$+0.919 \cdot 10^{-9}$	0 7 0.999995

TABLE 1 (PART 3)

$u = 2.0$	$v = 5.0$	$w = 1.0$
$\bar{H} = 0.00$	$\bar{K} = 5.00$	$\bar{L} = 10.0$
$\tilde{R}$	RERR	IND N $\bar{P}$
$0.6184610273 \cdot 10^1$	$-0.780 \cdot 10^{-9}$	0 10 $0.500000 \cdot 10^{-5}$
$0.8185500434 \cdot 10^1$	$-0.900 \cdot 10^{-10}$	0 13 $0.500000 \cdot 10^{-2}$
$0.9733490650 \cdot 10^1$	$-0.119 \cdot 10^{-12}$	0 6 0.100000
$0.1172659410 \cdot 10^2$	$+0.211 \cdot 10^{-10}$	0 6 0.500000
$0.1545659369 \cdot 10^2$	$+0.910 \cdot 10^{-8}$	0 6 0.900000
$0.2295500292 \cdot 10^2$	$+0.285 \cdot 10^{-12}$	0 8 0.999000
$0.2902552953 \cdot 10^2$	$+0.241 \cdot 10^{-9}$	0 6 0.999995

TABLE 1 (PART 4)

$u = 2.0 \cdot 10^4$	$v = 2.0 \cdot 10^9$	$w = 1.0$
$\bar{H} = 0.0$	$\bar{K} = 2.0 \cdot 10^5$	$\bar{L} = 0.0$
$\tilde{R}$	RERR	IND N $\bar{P}$
$0.2137608898 \cdot 10^5$	$-0.379 \cdot 10^{-8}$	0 6 $0.500000 \cdot 10^{-5}$
$0.1253323942 \cdot 10^8$	$-0.374 \cdot 10^{-8}$	0 1 $0.500000 \cdot 10^{-2}$
$0.2513226958 \cdot 10^9$	$-0.580 \cdot 10^{-9}$	0 1 0.100000
$0.1348979507 \cdot 10^{10}$	$+0.942 \cdot 10^{-10}$	0 1 0.500000
$0.3289707270 \cdot 10^{10}$	$+0.697 \cdot 10^{-11}$	0 1 0.900000
$0.6581053496 \cdot 10^{10}$	$+0.541 \cdot 10^{-13}$	0 1 0.999000
$0.9129575506 \cdot 10^{10}$	$+0.222 \cdot 10^{-15}$	0 1 0.999995

#### IV. TEST RESULTS FOR ELLCOV AND ELINV3

Extensive testing was carried out to establish the accuracy claimed for ELLCOV and ELINV3 keeping in mind that inherent error plays a major role when  $D$  is large (see page 11). The tests compared ELLCOV results with the corresponding outputs from a double precision adaptive quadrature subroutine, DQAGS, which is contained in NSWCLIB [13]. For ELINV3, values of  $P$  ranging from  $10^{-20}$  to .9999999 were given with extensive ranges of the variables  $\bar{H}$ ,  $\bar{K}$ ,  $\bar{L}$ ,  $u$ ,  $v$  ( $w = 1$ ). An estimate  $\tilde{R}$  for the true value  $\bar{R}$  was found using ELINV3. ELLCOV was then used with  $\tilde{R}$  to compute  $\tilde{P}$  for comparison with the initial given value of  $P$ .

Testing using a Compaq Deskpro 386/20 computer with a CYRIX numeric coprocessor showed that the average time to compute a value of  $P$  using ELLCOV was  $\sim 0.4$  seconds. The average time using ELINV3 to find a value  $\tilde{R}$  was  $\sim 1.1$  seconds requiring on the average approximately 6 iterations. The maximum observed number of iterations, 27, occurred for isolated cases in the range  $10^{-20} \leq P \leq 10^{-3}$ . The maximum observed time for ELINV3 was 25 seconds, also occurring for small values of  $P$ . All testing was done using double precision Fortran for the IBM PC.

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**APPENDIX A**

**DERIVATION OF (17) AND (25) – (31)**

## DERIVATION OF (17) AND (25) - (31)

DERIVATION OF (17):

Equation (17) holds when  $u = v = w$  and  $D \neq 0$  and is given by

$$P = \frac{4}{\sqrt{\pi}} E(D) \sum_1^n \frac{H_{2n-1}(D)/D}{(2n+1)!} R^{2n+1}, \quad D \equiv \sqrt{H^2 + K^2 + L^2}, \quad A(1)$$

where  $H_k(x)$  denotes the classical Hermite polynomial of degree  $k$ . From (10)

$$P = \frac{1}{2} \left\{ \operatorname{erf}(D+R) - \operatorname{erf}(D-R) - \frac{1}{\sqrt{\pi} D} [E(D-R) - E(D+R)] \right\}. \quad A(2)$$

From [9, p. A-3]

$$\operatorname{aerf}(D, R) \equiv \operatorname{erf}(D+R) - \operatorname{erf}(D-R) = \frac{4}{\sqrt{\pi}} E(D) \sum_{n=0}^{\infty} \frac{H_{2n}(D) R^{2n+1}}{(2n+1)!}. \quad A(3)$$

Using the property of the Hermite polynomials

$$\frac{d^n}{dx^n} E(x) = (-1)^n E(x) H_n(x), \quad [1, 22.11.7] \quad A(4)$$

and expanding  $E(D+R)$  about  $R=0$  gives

$$E(D+R) = E(D) \sum_{n=0}^{\infty} (-1)^n \frac{H_n(D) R^n}{n!}. \quad A(5)$$

With these results A(2) becomes

$$P = \frac{1}{2} \left\{ \frac{4}{\sqrt{\pi}} E(D) \sum_{n=0}^{\infty} \frac{H_{2n}(D) R^{2n+1}}{(2n+1)!} - \frac{2}{\sqrt{\pi}} \frac{E(D)}{D} \sum_{n=0}^{\infty} \frac{H_{2n+1}(D) R^{2n+1}}{(2n+1)!} \right\}, \quad A(6)$$

or

$$P = \frac{1}{\sqrt{\pi}} \frac{E(D)}{D} \sum_{n=0}^{\infty} \frac{R^{2n+1}}{(2n+1)!} [2D H_{2n}(D) - H_{2n+1}(D)]. \quad A(7)$$

Making use of the recurrence relation for Hermite polynomials, namely,

$$H_{n+1}(x) = 2x H_n(x) - 2n H_{n-1}(x), \quad H_0 = 1, \quad H_1 = 2x, \quad [1, 22.7.13] \quad A(8)$$

in A(7) yields A(1).

DERIVATION OF (25):

Equation (25) is given by

$$P = \frac{2}{\sqrt{\pi}} R (Rw/u)^2 E(L/\sqrt{2}) \sum_1 F_{2n+1} \quad A(9)$$

$$F_{2n+1} = \frac{1}{2n+1} [G_{2n-1} - 2(Rw/u)^2 F_{2n-1}], \quad n \geq 1 \quad A(9.1)$$

$$G_{2n-1} = \frac{2R^{2n-2}}{(2n-1)(2n-2)!} E(L/\sqrt{2}) H_{2n-2}(L) \quad A(9.2)$$

$$F_1 = 0, \quad H_0 = 1, \quad G_1 = 2 E(L/\sqrt{2}). \quad A(9.3)$$

Let

$$f(R) \equiv \int_{L-R}^{L+R} E(z) \left\{ 1 - e^{-(w/u)^2 [R^2 - (L-z)^2]} \right\} dz. \quad A(10)$$

Then, for  $H = K = 0$  and  $u = v$ , we have from (18) and (6)

$$P = \frac{1}{\sqrt{\pi}} f(R). \quad A(11)$$

Our aim is to obtain the Taylor series for  $f(R)$  about  $R = 0$  and also the recurrence relation for computing the successive terms of the series. From A(10) and (12)

$$f(R) = \frac{\sqrt{\pi}}{2} \operatorname{erf}(L, R) - \int_{L-R}^{L+R} E(z) e^{-(w/u)^2 [R^2 - (L-z)^2]} dz. \quad A(12)$$

Note that  $f(R)$  is an odd function of  $R$  so that  $f^{(2n)}(0) = 0$ ,  $n = 0, 1, 2, \dots$ , where

$$f^{(n)}(R) \equiv \frac{d^n}{dR^n} f(R).$$

Thus

$$f(R) = \sum_{n=0}^{\infty} \frac{f^{(2n+1)}(0) R^{2n+1}}{(2n+1)!}. \quad A(13)$$

Differentiating  $f(R)$  in A(12) gives

$$\begin{aligned} \frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(1)}(R) &= R \int_{L-R}^{L+R} E(z) e^{-(w/u)^2 [R^2 - (L-z)^2]} dz \\ &= R [Q(R) - f(R)], \quad f^{(1)}(0) = 0, \end{aligned} \quad A(14)$$

where, using A(3) with  $D = L$ , we have introduced the notation

$$Q(R) \equiv \frac{\sqrt{\pi}}{2} \operatorname{erf}(L, R) = 2 E(L) \sum_{n=0}^{\infty} \frac{H_{2n}(L) R^{2n+1}}{(2n+1)!} \quad [\text{See A(3)}]. \quad A(15)$$

Successive differentiations beginning with A(14) give

$$\begin{aligned} \frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(2)}(R) &= Q(R) - f(R) + R [Q^{(1)}(R) - f^{(1)}(R)] \\ \frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(3)}(R) &= 2 [Q^{(1)}(R) - f^{(1)}(R)] + R [Q^{(2)}(R) - f^{(2)}(R)] \\ \frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(4)}(R) &= 3 [Q^{(2)}(R) - f^{(2)}(R)] + R [Q^{(3)}(R) - f^{(3)}(R)] \\ &\vdots \\ \frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(n)}(R) &= (n-1) [Q^{(n-2)}(R) - f^{(n-2)}(R)] + R [Q^{(n-1)}(R) - f^{(n-1)}(R)]. \end{aligned}$$

Hence, it follows that

$$\frac{1}{2} \left(\frac{u}{w}\right)^2 f^{(2n+1)}(0) = 2n [Q^{(2n-1)}(0) - f^{(2n-1)}(0)], \quad A(16)$$

where, from A(15),

$$Q^{(2n-1)}(0) = 2 E(L) H_{2n-2}(L), \quad Q^{(1)}(0) = 2 E(L).$$

Now define  $F_{2n+1}$  by

$$2 R (R \frac{w}{u})^2 E(L\sqrt{2}) F_{2n+1} = \frac{f^{(2n+1)}(0)}{(2n+1)!} R^{2n+1}, \quad n = 1, 2, \dots \quad A(16)$$

Then, from A(11), A(13), and A(16)

$$P = \frac{2}{\sqrt{\pi}} R (R \frac{w}{u})^2 E(L/\sqrt{2}) \sum_{n=1}^{\infty} F_{2n+1}, \quad F_1 = 0, \quad A(17)$$

where, using A(15) and A(16),

$$\begin{aligned} F_{2n+1} &= 2n \left[ \frac{Q^{(2n-1)}(0)}{(2n-1)!} - 2 \left( \frac{w}{u} \right)^2 \frac{\frac{1}{2} \left( \frac{u}{w} \right)^2 f^{(2n-1)}(0)}{(2n-1)!} \right] \frac{R^{2n-2}}{2n(2n+1)} \\ &= \frac{1}{2n+1} [G_{2n-1} - 2 (R \frac{w}{u})^2 F_{2n-1}], \quad n \geq 1, \end{aligned} \quad A(17.1)$$

and

$$G_{2n-1} = \frac{2 E(L/\sqrt{2}) R^{2n-2}}{(2n-1)!} H_{2n-2}(L). \quad A(17.2)$$

Also

$$F_1 = 0, \quad H_0(L) = 1, \quad G_1 = 2 E(L/\sqrt{2}), \quad A(17.3)$$

where the first relation follows from setting  $n = 0$  in A(16) and using A(14).

#### DERIVATION OF (26) - (27):

When  $H = K = L = 0$  and  $u = v$ , one obtains from (21) for  $u > w$

$$P = \operatorname{erf} R - R E(R w/u) \frac{\operatorname{erf}(RZ)}{RZ}, \quad Z \equiv \sqrt{|1 - (w/u)^2|}. \quad A(18)$$

Then using

$$\operatorname{erf}(RZ) = \frac{2}{\sqrt{\pi}} E(RZ) \sum_{n=0}^{\infty} \frac{2^n}{1 \cdot 3 \cdots (2n+1)} (RZ)^{2n+1}, \quad [1, \text{p.297}]$$

in A(18) yields (26),

$$P = P_B - \frac{2R}{\sqrt{\pi}} E(R) \sum_{n=1}^{\infty} \frac{2^n}{3 \cdots (2n+1)} (RZ)^{2n}, \quad u \geq w,$$

where

$$P_B = \operatorname{erf} R - \frac{2}{\sqrt{\pi}} R E(R) \quad [\text{See (11)}].$$

For  $w > u$ , one obtains from (23)

$$P = \operatorname{erf} R - \frac{2R}{\sqrt{\pi}} E(R) \frac{\operatorname{daw}(RZ)}{RZ}, \quad L = 0, \quad A(19)$$

where

$$\operatorname{daw}(x) \equiv E(x) \int_0^x e^{t^2} dt \quad (\text{Dawson's integral}). \quad [1, \text{p.298}] \text{ and } [8]$$

Also

$$\begin{aligned} \text{daw}(x) &= \int_0^x e^{(t^2 - x^2)} dt = x \int_0^{\pi/2} E(x \cos \theta) \cos \theta d\theta, \quad t = x \sin \theta \\ &= \sum_0^n (-1)^n \frac{x^{2n+1}}{n!} \int_0^{\pi/2} \cos^{2n+1} \theta d\theta \\ &= \sum_0^n (-1)^n \frac{x^{2n+1}}{n!} \frac{2^n n!}{1 \cdot 3 \cdot 5 \cdots 2n+1}. \end{aligned}$$

Using this result, with  $x = RZ$ , in A(19) above gives (27),

$$P = P_B - \frac{2R}{\sqrt{\pi}} E(R) \sum_1^n \frac{(-2)^n}{1 \cdot 3 \cdots (2n+1)} (RZ)^{2n}, \quad w \geq u.$$

DERIVATION OF (28) - (29):

For  $H = K = 0$  and  $u = v$ , with  $S \geq 5Z$ , we derive the following relations:

$$P = P_B - \frac{E(R-L)}{2FS} \left\{ \frac{RZ^2}{\sqrt{\pi}} \left[ 4R^2Z^2 \frac{[1 - E(2\sqrt{RL})]}{4RL} + [1 + e^{-4RL}] \right] - \text{efsz} \right\}, \quad u > w \quad A(20)$$

$$\text{erfc} x \equiv 1/\sqrt{\pi} - x e^{x^2} \text{erfc} x, \quad x \geq 4 \quad A(20.1)$$

$$\text{efsz} \equiv F \text{erfc}(S/Z) - S e^{-4RL} \text{erfc}(F/Z), \quad A(20.2)$$

and

$$P = P_B - \frac{E(R-L)}{2FS} \left\{ \frac{RZ^2}{\sqrt{\pi}} \left[ 4R^2Z^2 \frac{[1 - E(2\sqrt{RL})]}{4RL} - [1 + e^{-4RL}] \right] + \frac{Z^2}{\sqrt{\pi}} \text{bdaw}1 \right\}, \quad w > u \quad A(21)$$

$$\text{daw}(y) \simeq 1/(2y) [1 + \text{Frac}(y)/y^2], \quad y \geq 5 \quad [2] \quad A(21.1)$$

$$\text{bdaw}1 = S/F^2 \text{Frac}(F/Z) - F/S^2 E(2\sqrt{RL}) \text{Frac}(S/Z), \quad A(21.2)$$

with

$$Z \equiv \sqrt{|1 - (w/u)^2|}, \quad S \equiv L - RZ^2, \quad F \equiv L + RZ^2. \quad A(22)$$

For the derivation of (28), which is A(20), first consider (20), with  $u > w$ ,

$$P = \frac{1}{2} \text{aerf}(L, R) - \frac{E(L-R)}{2Z} \left[ E\left(i\frac{S}{Z}\right) \text{erfc}\left(\frac{S}{Z}\right) - e^{-4RL} E\left(i\frac{F}{Z}\right) \text{erfc}\left(\frac{F}{Z}\right) \right], \quad L \neq 0, \quad S > 0. \quad A(23)$$

The quantity in square brackets in A(23) can now be written, using A(20.1) and A(20.2), as

$$\frac{Z[F - S e^{-4RL}]}{\sqrt{\pi} FS} - \frac{Z}{FS} \text{efsz}.$$

Substituting this result into A(23) and also adding and subtracting

$$\frac{2}{\sqrt{\pi}} R \left[ \frac{1 - e^{-4RL}}{4RL} \right] E(L-R) \frac{2(L^2 - R^2 Z^4)}{2FS}, \quad A(24)$$

gives, after using A(22),

$$P = P_B - \frac{E(L-R)}{2FS} \left\{ 4RL^2 \frac{[1 - e^{-4RL}]}{\sqrt{\pi} 4RL} + \frac{RZ^2}{\sqrt{\pi}} [1 + e^{-4RL}] - \text{efsz} \right\} + 2R \frac{[1 - e^{-4RL}]}{\sqrt{\pi} 4RL} E(L-R) \frac{2(L^2 - R^2 Z^4)}{2FS}, \quad A(25)$$

where  $P_B$  is given by (10). Carrying out the obvious cancellation in A(25), followed by some minor rearrangements gives A(20).

In order to derive (29) above begin with (22), where  $w > u$ , i.e.,

$$P = \frac{1}{2} \text{aerf}(L, R) - \frac{E(L-R)}{\sqrt{\pi} Z} \left[ \text{daw}\left(\frac{F}{Z}\right) - e^{-4RL} \text{daw}\left(\frac{S}{Z}\right) \right], \quad L \neq 0. \quad A(26)$$

The quantity in square brackets in A(26) can now be written, using A(21.1) and A(21.2), as

$$\frac{Z}{2FS} \left\{ S - F e^{-4RL} + Z^2 \left[ \frac{S}{F^2} \text{Frac}(F/Z) - e^{-4RL} \frac{F}{S^2} \text{Frac}(S/Z) \right] \right\}.$$

Substituting this result into A(26) and adding and subtracting A(24) gives, using A(22),

$$P = P_B - \frac{E(L-R)}{2FS\sqrt{\pi}} \left\{ 4RL^2 \frac{[1 - e^{-4RL}]}{4RL} - RZ^2 [1 + e^{-4RL}] + Z^2 \text{bdaw}1 \right\} + 2R \frac{[1 - e^{-4RL}]}{\sqrt{\pi} 4RL} E(L-R) \frac{2(L^2 - R^2 Z^4)}{2FS}. \quad A(27)$$

Carrying out the obvious cancellation in A(27), followed by some minor rearrangements, gives A(21) or (29).

#### DERIVATION OF (30):

Equation (30) follows directly from (23), where  $L = 0$ , by noting that  $\text{aerf}(L, R) = 2 \text{erf} R$ , by multiplying and dividing by  $R$  after the minus sign, and by using  $\text{dxdaw} \equiv \text{daw}(x)/x$ .

#### DERIVATION OF (31):

For the derivation of (31) use A(10) and A(11) to obtain

$$P = \frac{1}{\sqrt{\pi}} \int_{L-R}^{L+R} E(z) \left\{ 1 - e^{-(w/u)^2 [R^2 - L^2]} e^{-(w/u)^2 [2Lz - z^2]} \right\} dz. \quad A(28)$$

Let

$$y \equiv e^{-(w/u)^2 [2Lz - z^2]},$$

and make the substitution  $z = i \frac{u}{w} \xi$  ( $i \equiv \sqrt{-1}$ ) to obtain

$$y \equiv e^{2(-i\frac{w}{u}L)\xi - \xi^2}. \quad A(29)$$

Using the relation

$$e^{2xt - t^2} = \sum_0 \frac{H_n(x) t^n}{n!}, \quad [1, p. 784]$$

and A(29), A(28) becomes

$$P = \frac{1}{\sqrt{\pi}} \int_{L-R}^{L+R} E(z) \left\{ 1 - e^{-(w/u)^2 [R^2 - L^2]} \sum_0 \frac{H_n(-i\frac{w}{u}L)(\frac{w}{iu}z)^n}{n!} \right\} dz. \quad A(30)$$

With obvious modifications to A(30) the result for (31) follows, namely,

$$P = \frac{1}{2} \left\{ \left( 1 - e^{-(w/u)^2 [R^2 - L^2]} \right) \text{erf}(L, R) - e^{-(w/u)^2 [R^2 - L^2]} \sum_1 \frac{H_n(-iLw/u)}{n!} \frac{2}{\sqrt{\pi}} \int_{L-R}^{L+R} E(t) \left( -\frac{iw}{u} \right)^n t^n dt \right\}. \quad A(31)$$

Equation A(31) is evaluated with the use of recurrence relations. Let

$$\begin{aligned} T_n &\equiv \frac{2}{\sqrt{\pi}} \int_{L-R}^{L+R} E(t) t^n dt / n! \\ &= \frac{(L-R)^{n-1} E(L-R) - (L+R)^{n-1} E(L+R)}{\sqrt{\pi} n!} + \frac{1}{2n} T_{n-2} \\ &= \frac{1}{2n} T_{n-2} + \frac{1}{\sqrt{\pi}} \frac{E(L-R)}{n!} \left[ (L-R)^{n-1} - e^{-4LR} (L+R)^{n-1} \right], \quad n \geq 2, \end{aligned}$$

where

$$T_0 = \text{erf}(L, R), \quad T_1 = \frac{1}{\sqrt{\pi}} E(L-R) [1 - e^{-4LR}].$$

Let

$$U_n \equiv \left( \frac{w}{u} \right)^n (-i)^n H_n(-i\frac{w}{u}L). \quad A(32)$$

Then using the recurrence relation for Hermite polynomials given in A(8), we have

$$U_n = \left[ (-i) \frac{2w}{u} (-i) \frac{w}{u} L \right] U_{n-1} + 2(n-1) \left( \frac{w}{u} \right)^2 U_{n-2}, \quad n \geq 2,$$

or

$$U_n = 2 \left( \frac{w}{u} \right)^2 \left[ -L U_{n-1} + (n-1) U_{n-2} \right], \quad n \geq 2,$$

with

$$U_0 = 1, \quad U_1 = -2 \left( \frac{w}{u} \right)^2 L.$$

Therefore A(31) can also be written as

$$P = \frac{1}{2} \left\{ \left( 1 - e^{-(w/u)^2 [R^2 - L^2]} \right) \text{erf}(L, R) - e^{-(w/u)^2 [R^2 - L^2]} \sum_1 T_n U_n \right\}. \quad A(33)$$

**APPENDIX B**

**FORTRAN LISTINGS FOR ELLCOV AND SUPPORTING ROUTINES**



# **FORTTRAN LISTINGS FOR ELLCOV AND SUPPORTING ROUTINES**

Below we give a summary of the various subprograms that are used for computing P. These subprograms are listed in this appendix, except for those which are contained in NSWCLIB [13]. The NSWCLIB routines are identified below with a superscript \*. All subprograms are given in double precision.

## REFERENCING OF ROUTINES USED TO COMPUTE P

ELLCOV	uses:	AERF*	CH	CIRCV*	DEPSLN*	DPMPAR*	EQSIG
		PKILL*	RQUAD	SEQHZ3	SQUAD	TQUA1	
EQSIG	uses:	AERF*	DXPARG*	ERF5	HSEXP		
FN2	uses:	CIRCV*	PKILL*				
RQUAD	uses:	FN2					
SEQHZ3	uses:	AERF*	BDAW1	DAW*	DXDAW	DXPARG*	EQSIG
		ERF*	ERFC0*	ERFCR	HSEXP*		
SQUAD	uses:	FN2					
TQUA1	uses:	FN2					

DOUBLE PRECISION FUNCTION ELLCOV(R,HX,HY,HZ,SX,SY,SZ,  
\* XK0,XK2,SS)

C-----  
C (X,Y,Z) IS AN ELEMENT OF A CARTESIAN COORDINATE SYSTEM.  
C ELLCOV RETURNS THE PROBABILITY OF A SHOT FALLING, UNDER AN  
C ELLIPSOIDAL NORMAL DISTRIBUTION, IN A SPHERE OF RADIUS R WITH  
C CENTER (HX,HY,HZ) AND RADIUS R. THE DISTRIBUTION HAS MEAN  
C (0,0,0) AND STANDARD DEVIATIONS SX, SY AND SZ IN THE X,Y,Z  
C DIRECTIONS, RESPECTIVELY. THE INPUT PARAMETERS ARE R,HX,HY,HZ,  
C SX,SY,SZ,XK0,XK2,SS, WHERE XK0 = HX\*HX+HY\*HY+HZ\*HZ,  
C XK2 = SQRT(XK0) AND SS = MAX(SX,SY,SZ). A 24TH ORDER GAUSSIAN  
C NUMERICAL INTEGRATION IS CARRIED OUT IN RQUAD AND SQUAD.  
C  
C THE OUTPUT ELLCOV IS ACCURATE TO AT LEAST 6-SIGNIFICANT DIGITS  
C WHEN 1D-20 .LT. ELLCOV .LT. .9999999, AND (H/SX)\*\*2+(K/SY)\*\*2+  
C (L/SZ)\*\*2 .LT. 2/DPMPAR(1).  
C  
C REF: INTEGRATION OF THE TRIVARIATE NORMAL DISTRIBUTION OVER AN  
C OFFSET SPHERE AND AN INVERSE PROBLEM. NSWV TR. 87-27, 2/1988.  
C REF: SIGNIFICANT DIGIT COMPUTATION OF THE ELLIPSOIDAL COVERAGE  
C FUNCTION AND ITS INVERSE. NAVSWC TR. 91-487, 8/91.  
C-----

EXTERNAL	AERF ,CH ,DEPSLN ,DPMPAR ,EQSIG ,PKILL
EXTERNAL	RQUAD ,SEQHZ3 ,SQUAD ,TQUA1 ,CIRCV

C-----  
C DOUBLE PRECISION AERF ,DEPSLN ,DPMPAR ,EQSIG  
C DOUBLE PRECISION X(12) ,Y(12)  
C DOUBLE PRECISION K ,L  
C-----

DOUBLE PRECISION	A	,AH	,AK	,AL	,A2	,A3
DOUBLE PRECISION	B	,BH	,BK	,BL	,B1	,C5
DOUBLE PRECISION	C6	,C7	,C8	,C9	,D	,DEP
DOUBLE PRECISION	EPS	,E1	,FH	,FK	,FL	,F2
DOUBLE PRECISION	H	,HH	,HK	,HL	,HX	,HY
DOUBLE PRECISION	HZ	,PY	,R	,R1	,R2	,R3
DOUBLE PRECISION	SS	,SX	,SY	,SZ	,S1	,S2
DOUBLE PRECISION	S3	,T5	,T8	,W1	,XK0	,XK2
DOUBLE PRECISION	XK2	,XK7	,ZH	,ZL	,Z4	

C-----  
C X(\*),Y(\*) -- GAUSSIAN ABCISSAS AND WEIGHTS OF ORDER 24 ON (-1,1).  
C-----

DATA	X(1)	/6.40568928626056D-2/	,X(2)	/.191118867473616D0/
*	X(3)	/.315042679696163D0/	,X(4)	/.433793507626045D0/
*	X(5)	/.545421471388840D0/	,X(6)	/.648093651936976D0/
*	X(7)	/.740124191578554D0/	,X(8)	/.820001985973903D0/
*	X(9)	/.886415527004401D0/	,X(10)	/.938274552002733D0/
*	X(11)	/.974728555971309D0/	,X(12)	/.995187219997021D0/

```

DATA Y(1) /.127938195346752D0/ ,Y(2) /.125837456346828D0/,
*      Y(3) /.121670472927803D0/ ,Y(4) /.115505668053726D0/,
*      Y(5) /.107444270115966D0/ ,Y(6) /9.76186521041139D-2/,
*      Y(7) /8.61901615319533D-2/ ,Y(8) /7.33464814110803D-2/,
*      Y(9) /5.92985849154368D-2/ ,Y(10) /4.42774388174198D-2/,
*      Y(11) /2.85313886289337D-2/ ,Y(12) /1.23412297999872D-2/

```

```

C-----
DATA B1 /0.5641895835477563D0/,C5 /7.0D0/,
*      C6 /0.3989422804014327D0/,C7 /0.7071067811865475D0/,
*      C8 /1.414213562373095D0/ ,C9 /9.6D0/, F2 /1D1/

```

```

C-----
C      B1 = 1/SQRT(PI),    C6 = 1/SQRT(2PI)
C-----

```

```

EPS = 10*DPMPAR(1)
T8 = 1D2*DPMPAR(2)
Z4 = MAX(T8,1D-25*1D-25)
DEP = -DEPSLN(0)
N = 12
J1 = 0
H = ABS(HX)
K = ABS(HY)
L = ABS(HZ)
S1 = SX
S2 = SY
S3 = SZ
PY = 0.D0
ELLCOV = 0.0D0
E1 = 1.5D0*SX*SY*SZ*Z4/C6
XK7 = R*R*R
IF (XK7 .LE. E1) RETURN
A3 = (XK2 - R)*C7/SS
A = EXP(-A3*A3)
IF (XK2 .LT. R) GO TO 5
IF (XK7*A .LE. E1) RETURN
GO TO 10

```

```

C-----
5  PY = EQSIG(R,XK0,XK2,SS,EPS,DEP,A)
   E1 = DMAX1(1D-11, 5*EPS)
   IF (PY .LT. 1.0D0 - E1) GO TO 10
   ELLCOV = 1.0D0
   RETURN
10 IF (SX .NE. SY .OR. SY .NE. SZ) GOTO 15

```

```

C-----
C      S1 = S2 = S3.
C-----

```

```

ELLCOV = PY
IF (R .GT. XK2) RETURN
ELLCOV = EQSIG(R,XK0,XK2,SS,EPS,DEP,A)
RETURN

```

```

C-----
C      SMALL R
C-----
15  R1 = R/S1
    R2 = R/S2
    R3 = R/S3
    HH = H/S1
    HK = K/S2
    HL = L/S3
    AH = R1*R1
    BH = HH*HH
    AK = R2*R2
    BK = HK*HK
    AL = R3*R3
    BL = HL*HL
    T5 = AH*(BH - 1D0) + AK*(BK - 1D0) + AL*(BL - 1D0)
    IF (ABS(T5) .GT. 1D-3) GOTO 20
    W1 = 4*(AH*AH*(BH - .5D0) + AK*AK*(BK - .5D0) +
*     AL*AL*(BL - .5D0))
    AH = (T5*T5 + ABS(W1))/280
    IF (AH .GT. MAX(EPS,2.5D-8)) GOTO 20
    ELLCOV = B1*R1*R2*R3/(3*C7)*(1.D0 + T5/10 + (T5*T5 - W1)/280)*
*     EXP(-(BH + BK + BL)/2)
    RETURN
20  J1 = 3
    IF (SX .EQ. SY .AND. H + K .EQ. 0.D0) GOTO 25
    J1 = 2
    IF (SX .EQ. SZ .AND. H + L .EQ. 0.D0) GOTO 25
    J1 = 1
    IF (SZ .NE. SY .OR. L + K .NE. 0.D0) GOTO 30
25  CALL CH(J1,H,K,L,S1,S2,S3)
C-----
C      S1 = S2 AND H = K = 0.
C-----
    CALL SEQHZ3(R,L,S1,S3,EPS,DEP,XK0,A,PY,ELLCOV,KKK)
    RETURN
C-----
30  J = 2
    II = 0
    AH = MAX(-C5,(HH - R1)*C7)
    IF (AH .GT. C9) RETURN
    BH = MIN(F2,HH*C7)
    AK = MAX(-C5,(HK - R2)*C7)
    IF (AK .GT. C9) RETURN
    BK = MIN(F2,HK*C7)
    AL = MAX(-C5,(HL - R3)*C7)
    IF (AL .GT. C9) RETURN
    BL = MIN(F2,HL*C7)

```

```

T8 = MAX(1D-42,T8)
ZL = MIN(EPS/30,1D-12)
CALL TQUA1(AH,BH,N,X,R,K,L,H,S2,S3,S1,PY,T8,DEP,FH)
IF (AH .GT. -6D0) GOTO 35
IF ((HH - C8*AH)**2 .GT. R1*R1*ZL) GOTO 35
H = 1
GOTO 110
35  T5 = BH - AH
    N1 = 0
    IF (T5 .NE. 0.D0) GOTO 40
    N1 = 1
    GOTO 45
40  J1 = 1
    A = AH
    B = BH
45  CALL TQUA1(AK,BK,N,X,R,L,H,K,S3,S1,S2,PY,T8,DEP,FK)
    IF (AK .GT. -6D0) GOTO 50
    IF ((HK - C8*AK)**2 .GT. R2*R2*ZL) GOTO 50
    H = 1
    J1 = 2
    GOTO 110
50  A2 = BK - AK
    N2 = 0
    IF (A2 .NE. 0.D0) GOTO 55
    N2 = 1
    GOTO 85
55  IF (N1 .NE. 0) GOTO 65
    IF (AH .LT. -2D0 .AND. AK - AH .GT. 4D0) GOTO 85
    IF (AK .LT. -2D0 .AND. AH - AK .GT. 4D0) GOTO 65
    W1 = T5 - A2
    IF (ABS(W1) .GT. 5D2*EPS) GOTO 60
    IF (AH .GT. AK .AND. AH .LT. -2.D0) GOTO 85
60  IF (W1) 65,65,85
65  J1 = 2
    A = AK
    B = BK
    CALL TQUA1(AL,BL,N,X,R,H,K,L,S1,S2,S3,PY,T8,DEP,FL)
    IF (AL .GT. -6D0) GOTO 70
    IF ((HL - C8*AL)**2 .GT. R3*R3*ZL) GOTO 70
    H = 1
    J1 = 3
    GOTO 110
70  T5 = BL - AL
    IF (T5 .NE. 0.D0) GOTO 75
    GOTO 110
75  IF (N2 .NE. 0) GOTO 105
    IF (AK .LT. -2D0 .AND. AL - AK .GT. 4D0) GOTO 110
    IF (AL .LT. -2D0 .AND. AK - AL .GT. 4D0) GOTO 105
    W1 = T5 - A2

```

```

      IF (ABS(W1) .GT. 5D2*EPS) GOTO 80
      IF (AK .GT. AL .AND. AK .LT. -2.D0) GOTO 110
80   IF (W1) 110,105,105
85   CALL TQUA1(AL,BL,N,X,R,H,K,L,S1,S2,S3,PY,T8,DEP,FL)
      IF (AL .GT. -6D0) GOTO 90
      IF ((HL - C8*AL)**2 .GT. R3*R3*ZL) GOTO 90
      II = 1
      J1 = 3
      GOTO 110
90   A2 = BL - AL
      IF (A2 .NE. 0.D0) GOTO 95
      IF (N1 .NE. 1) GOTO 110
      ELLCOV = 0.D0
      RETURN
95   IF (N1 .EQ. 1) GOTO 105
      IF (AH .LT. -2D0 .AND. AL - AH .GT. 4D0) GOTO 110
      IF (AL .LT. -2D0 .AND. AH - AL .GT. 4D0) GOTO 105
      W1 = T5 - A2
      IF (ABS(W1) .GT. 5D2*EPS) GOTO 100
      IF (AH .GT. AL .AND. AH .LT. -2.D0) GOTO 110
100  IF (W1) 105,105,110
105  J1 = 3
      A = AL
      B = BL
C-----
110  CALL CH(J1,H,K,L,S1,S2,S3)
      IF (S1 .NE. S2) GOTO 115
C-----
C      S1 = S2,  J = 1.
C-----
      J = 1
      D = SQRT(H*H + K*K)/S1
      GO TO 125
115  IF (H + K .NE. 0.D0) GOTO 125
C-----
C      H = K = 0,  J = 0.
C-----
      IF (S1 .GT. S2) GO TO 120
      W1 = S1
      S1 = S2
      S2 = W1
120  D = S2/S1
      J = 0
125  IF (II .EQ. 0) GOTO 135
C-----
C  SEE P.10 OF REPT. 87-27.
C-----
      IF (J .LT. 2) GO TO 130
      CALL PKILL(R,S1,S2,H,K,ELLCOV)

```

```

        RETURN
130  CALL CIRCVR(R/S1,D,J,ELLCOV,IER)
        RETURN
C-----
C  PKILL OR CIRCVR .GT. 1 - 1E-8 FOR ALL T .GE. T8.
C-----
135  PY = 0.0D0
      XK7 = DMAX1(S1,S2)
      T8 = C5*XK7 + SQRT(H*H + K*K)
      T8 = R*R - T8*T8
      ZL = L/(C8*S3)
      IF (T8 .LT. 0.0D0) GO TO 140
      A3 = SQRT(T8)
      ZH = A3/(C8*S3)
      T8 = ZL - ZH
      IF (T8 .GE. B) GO TO 140
      B = T8
      PY = AERF(ZL,ZH)/2
      ELLCOV = PY
      IF ((1.D0 - PY) .LT. E1) RETURN
      IF (B - A .LE. ABS(B + A)*DMAX1(1D-9,EPS)) RETURN
C-----
C  OBTAIN SHARP INTEGRATION LIMITS FOR A AND B.
C-----
140  A2 = B - A
      XK7 = A
      T8 = B
      CALL SQUAD(A,B,W1,N,X,Y,R,H,K,L,S1,S2,S3,EPS,DEP,
      *  J,D,PY,IL)
      IF (W1 .LT. Z4) GOTO 145
C-----
C  IF A AND B ARE UNCHANGED BY SQUAD, ELLCOV = W1 + PY.
C-----
      IF(ABS(B - A) .LT. A2*(1.D0 - EPS)) GOTO 150
145  ELLCOV = PY + W1
      RETURN
C-----
C  START OF GAUSSIAN INTEGRATION.
C-----
C  I1 .GE. 1. GIVES NO. OF SUBINTERVALS OVER WHICH GAUSSIAN
C  NUMERICAL INTEGRATION IS APPLIED. GENERALLY I1 = 1. HIGHER
C  VALUES USED ONLY FOR CHECKING PURPOSES.
C-----
150  I1 = 1
      CALL RQUAD(A,B,ELLCOV,I1,N,X,Y,R,H,K,L,S1,S2,S3,DEP,J,D)
      ELLCOV = B1*ELLCOV + PY
      IF (ELLCOV .GT. 1.0D0) ELLCOV = 1.0D0
      RETURN
      END

```

## DOUBLE PRECISION FUNCTION BDAW1(XM,XP,DEL,T)

```

C-----
C   LET F1 = XP/DEL, S0 = XM/DEL.
C   DAW(X) = EXP(-X*X) * INTEGRAL (FROM 0 TO X) EXP(W*V') DW. BDAW1
C   GIVES THE QUANTITY (XM/XP**2) FRAC(XP) - T*(XP/XM**2) FRAC(XM),
C   WHERE FRAC(X) APPEARS IN THE MINIMAX RATIONAL APPROXIMATION
C   GIVEN FOR DAW(X) BY (1/(2X) + 1/(2 X**3)) FRAC(X), WHERE X .GE. 5.
C   BDAW1 IS CALLED FROM SEQH23, WHICH IS CALLED BY ELLCOV.
C   EVALUATION OF DAWSON'S INTEGRAL FOR ALL REAL X BY DAW(X) IS BASED
C   ON RATIONAL CHEBYSHEV APPROXIMATIONS PUBLISHED IN MATH. COMP.
C   24, 171-178(1970) BY CODY, PACIOREK AND THACHER.
C-----

```

```

C-----
C   DIMENSION          P4(7) ,Q4(6)
C-----

```

```

C   DOUBLE PRECISION  DEL ,FRM ,FRP ,P4 ,Q4 ,T
C   DOUBLE PRECISION  XLG ,XM ,XP ,ZM2 ,ZP2
C-----

```

```

C   DATA XLG/16777216.0D0/
C-----

```

```

C   COEFFICIENTS FOR R(6,6) APPROXIMATION,
C   IN J-FRACTION FORM, USED FOR ABS(X) .GT. 5.0
C-----

```

```

C   DATA P4(1)/-.315576735766984D+02/, P4(2)/-.100791496592972D+02/,
C   *      P4(3)/-.710713709224200D+01/, P4(4)/-.596879853243925D+01/,
C   *      P4(5)/-.449773645376092D+01/, P4(6)/-.249999965398199D+01/,
C   *      P4(7)/.499999999999330D+00/
C   DATA Q4(1)/.168874162155616D+03/, Q4(2)/.698280748271071D+01/,
C   *      Q4(3)/-.213029621139181D+02/, Q4(4)/-.712157348463305D+01/,
C   *      Q4(5)/-.250005973192356D+01/, Q4(6)/.750000000715687D+00/
C-----

```

```

C-----
C   FRP = 0.0D0
C   BDAW1 = 0.0D0
C   IF (DEL*XLG .LE. ABS(XM)) RETURN
C   IF (DEL*XLG .LE. XP) GOTO 10
C   ZP2 = (DEL/XP)**2
C   DO 5 I = 1, 6
C 5   FRP = ZP2*Q4(I) / (ZP2*(P4(I) + FRP) + 1)
C   FRP = P4(7) + FRP
C 10 FRM = 0.0D0
C   IF (T .EQ. 0.0D0) GOTO 25
C   ZM2 = (DEL/XM)**2
C   DO 15 I = 1, 6
C 15  FRM = ZM2*Q4(I) / (ZM2*(P4(I) + FRM) + 1)
C   FRM = P4(7) + FRM
C 20 BDAW1 = XM*FRP/XP**2 - T*XP*FRM/XM**2
C   RETURN
C 25 BDAW1 = XM*FRP/XP**2
C   RETURN
C   END

```



```

SUBROUTINE CH(J,H,K,L,S1,S2,S3)
C-----
C  BASED ON THE VALUE OF J (=1,2,3) H,K,L AND S1,S2,S3 ARE
C  INTERCHANGED. USED IN ELLCOV.
C-----
      DOUBLE PRECISION  K      ,L
C-----
      DOUBLE PRECISION  H      ,S1  ,S2  ,S3  ,X
C-----
      IF (J .EQ. 3) RETURN
      IF (J .EQ. 2) GO TO 5
      X = H
      H = L
      L = X
      X = S1
      S1 = S3
      S3 = X
      RETURN
5    X = K
      K = L
      L = X
      X = S2
      S2 = S3
      S3 = X
10  RETURN
      END

```

DOUBLE PRECISION FUNCTION DXDAW(X)

C-----  
 C THIS FUNCTION COMPUTES VALUES OF THE FUNCTION -  
 C  $\exp(-X \cdot X) \cdot (1/X) \cdot \text{INTEGRAL (FROM 0 TO X) } \exp(T \cdot T) \text{ DT,}$   
 C DEFINED FOR ALL REAL ARGUMENTS. USED IN SEQHZ3.  
  
 C THE MAIN COMPUTATION INVOLVES EVALUATION OF RATIONAL CHEBYSHEV  
 C APPROXIMATIONS PUBLISHED IN MATH. COMP. 24, 171-178(1970) BY  
 C CODY, PACIOREK AND THACHER.

C-----  
 DOUBLE PRECISION P1(9), Q1(9), P2(8), Q2(7), P3(8), Q3(7), P4(7), Q4(6)  
 DOUBLE PRECISION FRAC, SUMP, SUMQ, W2, X, Y, XLARGE

C-----  
 DATA XLARGE/16777216.0D0/

C-----  
 C COEFFICIENTS FOR R(8,8) APPROXIMATION,  
 C USED FOR ABS(X) .LT. 2.5

C-----  
 DATA P1(1)/.100000000000000D+01/, P1(2)/-.135599049815353D+00/,  
 \* P1(3)/.456738974064825D-01/, P1(4)/-.258323495918057D-02/,  
 \* P1(5)/.360079463580992D-03/, P1(6)/-.944375029163387D-05/,  
 \* P1(7)/.634674256878843D-06/, P1(8)/-.711645839183817D-08/,  
 \* P1(9)/.977985913592343D-10/  
 DATA Q1(1)/.100000000000000D+01/, Q1(2)/.531067616851310D+00/,  
 \* Q1(3)/.133052308640737D+00/, Q1(4)/.206907491644210D-01/,  
 \* Q1(5)/.220437428972266D-02/, Q1(6)/.166706801664365D-03/,  
 \* Q1(7)/.887964712053131D-05/, Q1(8)/.311750854173480D-06/,  
 \* Q1(9)/.574807177698046D-08/

C-----  
 C COEFFICIENTS FOR R(7,7) APPROXIMATION,  
 C IN J-FRACTION FORM, USED FOR  
 C 2.5 .LE. ABS(X) .LT. 3.5

C-----  
 DATA P2(1)/-.150695651187161D+01/, P2(2)/.293365747395449D+02/,  
 \* P2(3)/-.400000893643550D+02/, P2(4)/-.757931918089369D-01/,  
 \* P2(5)/-.889106479747812D+01/, P2(6)/.152644099623699D+02/,  
 \* P2(7)/-.597678086823489D+01/, P2(8)/.500236896088668D+00/  
 DATA Q2(1)/-.673106069744813D+00/, Q2(2)/.124486788262252D+04/,  
 \* Q2(3)/.721193217600229D+01/, Q2(4)/.112461662024575D+03/,  
 \* Q2(5)/.729177556415532D+02/, Q2(6)/.115840292551888D+03/,  
 \* Q2(7)/.226064666074309D+00/

C-----  
 C COEFFICIENTS FOR R(7,7) APPROXIMATION,  
 C IN J-FRACTION FORM, USED FOR  
 C 3.5 .LE. ABS(X) .LE. 5.0

```

DATA P3(1)/ .476405645273229D+01/, P3(2)/-.266167674896399D+02/,
* P3(3)/-.916804879813552D+01/, P3(4)/-.150507703496692D+02/,
* P3(5)/ .506460153742231D+01/, P3(6)/-.498544802986608D+01/,
* P3(7)/-.149838042036691D+01/, P3(8)/ .499999902705054D+00/
DATA Q3(1)/ .287776122973187D+03/, Q3(2)/ .256105722342226D+02/,
* Q3(3)/ .751701277744067D+02/, Q3(4)/ .146515167783109D+03/,
* Q3(5)/ .330707724676114D+02/, Q3(6)/-.148715811787195D+01/,
* Q3(7)/ .250011459611839D+00/
C-----
C      COEFFICIENTS FOR R(6,6) APPROXIMATION,
C      IN J-FRACTION FORM, USED FOR ABS(X) .GT. 5.0
C-----
DATA P4(1)/-.315576735766984D+02/, P4(2)/-.100791496592972D+02/,
* P4(3)/-.710713709224200D+01/, P4(4)/-.596879853243925D+01/,
* P4(5)/-.449773645376092D+01/, P4(6)/-.249999965398199D+01/,
* P4(7)/ .499999999999330D+00/
DATA Q4(1)/ .168874162155616D+03/, Q4(2)/ .698280748271071D+01/,
* Q4(3)/-.213029621139181D+02/, Q4(4)/-.712157348463305D+01/,
* Q4(5)/-.250005973192356D+01/, Q4(6)/ .750000000715687D+00/
C-----
C
Y = X * X
IF (ABS(X) .GT. XLARGE) GO TO 35
IF (Y .GE. 6.25D0) GO TO 5
C-----
C      ABS(X) .LT. 2.5
C-----
SUMP = ((((((P1(9) * Y + P1(8)) * Y + P1(7)) * Y + P1(6))
1      * Y + P1(5)) * Y + P1(4)) * Y + P1(3)) * Y + P1(2))
2      * Y + P1(1)
SUMQ = ((((((Q1(9) * Y + Q1(8)) * Y + Q1(7)) * Y + Q1(6))
1      * Y + Q1(5)) * Y + Q1(4)) * Y + Q1(3)) * Y + Q1(2))
2      * Y + Q1(1)
DXDAW = SUMP / SUMQ
RETURN
C-----
C      2.5 .LE. ABS(X) .LT. 3.5
C-----
5 IF (Y .GE. 12.25D0) GO TO 15
FRAC = 0.0D0
DO 10 I = 1, 7
10 FRAC = Q2(I) / (P2(I) + Y + FRAC)
DXDAW = (P2(8) + FRAC) / Y
RETURN
C-----
C      3.5 .LE. ABS(X) .LT. 5.0
C-----

```

```

15 IF (Y .GE. 25.0D0) GO TO 25
   FRAC = 0.0D0
   DO 20 I = 1, 7
20  FRAC = Q3(I) / (P3(I) + Y + FRAC)
   DXDAW = (P3(8) + FRAC) / Y
   RETURN
C-----
C      5.0 .LE. ABS(X) .LE. XLARGE
C-----
25  W2 = 1.0D0 / X / X
   FRAC = 0.0D0
   DO 30 I = 1, 6
30  FRAC = Q4(I) / (P4(I) + Y + FRAC)
   FRAC = P4(7) + FRAC
   DXDAW = (0.5D0 + 0.5D0 * W2 * FRAC) / Y
   RETURN
C-----
C      XLARGE .LT. ABS(X)
C-----
35  DXDAW = 0.5D0 / Y
   RETURN
   END

```

```

DOUBLE PRECISION FUNCTION EQSIG(R3,XK0,XK2,S,EPS,DEP,A5)
C-----
C   EQSIG COMPUTES ELLCOV FOR EQUAL SIGMAS. XK0 = H*H+K*K+L*L,
C   XK2 = SQRT(XK0). EPS = 10*DPMPAR(1).
C   A = (XK2-R3)*SQRT(.5)/S, A5 = EXP(-A*A).
C-----
EXTERNAL  ERF5 ,HSEXP ,AERF ,DXPARG
C-----
DOUBLE PRECISION  AERF ,DXPARG
C-----
DOUBLE PRECISION  A3      ,A4      ,A5      ,A6      ,C7      ,DEP
DOUBLE PRECISION  E       ,EPS     ,G1      ,H2      ,H4      ,H5
DOUBLE PRECISION  H6      ,H7      ,P4      ,P5      ,Q5      ,R3
DOUBLE PRECISION  S       ,S1      ,T       ,V1      ,XK0     ,XK2
DOUBLE PRECISION  Z
C-----
DATA A4/1.1283 79167 09551 257D0/, C7/.70710 67811 86547 524D0/
C-----
C      A4 = 2/SQRT(PI)
C-----
      EQSIG = 0.D0
      H6 = R3*C7/S
      A6 = XK2*C7/S
      A3 = A6 - H6
      E = MAX(1D-11,EPS)
      IF (XK0 .NE. 0.0D0) GOTO 15
      IF (H6 .GT. .071D0) GOTO 10
C-----
C   D = 0 AND R3/(SQRT(2)*S) .LE. .071
C-----
      N = 3
      EQSIG = 1.D0
      A6 = 1.D0
      P5 = 2.D0*H6*H6
      Q5 = P5*H6/N
5      N = N + 2
      A6 = A6*P5/N
      EQSIG = EQSIG + A6
      IF (A6 .GT. E*EQSIG) GOTO 5
      EQSIG = A4*A5*Q5*EQSIG
      KKK = 13
      RETURN
C-----
C   D = 0 AND R3/(SQRT(2)*S) .GT. .071
C-----
10  CALL ERF5(-A3,A5,P4)
      EQSIG = P4 - A4*H6*A5
      KKK = 14
      RETURN

```

C-----  
 C D.NE. 0 AND R3/(SQRT(2)\*S) .GE. .425  
 C-----

```

15 IF (H6 .LT. .425D0) GOTO 30
   P5 = 4.0D0*A6*H6
   IF (A3 .LT. 4.5D0) GOTO 25
   IF (P5 .LT. DEP) GOTO 25
   S1 = H6/A6
   E = MAX(2.5D-8, EPS)
   Z = 1.D0
   N = -1
   H7 = 2*A3*A3
20  N = N + 2
   Z = -N*Z/H7
   S1 = S1 + Z
   IF (ABS(Z) .GT. E*ABS(S1)) GOTO 20
   S1 = S1 - .5D0*Z
   EQSIG = .25D0*A4*A5/A3*S1
   RETURN
25  P4 = AERF(A6,H6)
   V1 = -1.D0
   CALL HSEXP(-P5,V1,Q5)
   EQSIG = 0.5D0*P4 - A4*H6*A5*Q5
   KKK = 15
   RETURN
  
```

C-----  
 C D.NE. 0 AND R3/(SQRT(2)\*S) .LT. .425  
 C-----

```

30  T = A6*A6/2
   KKK = 16
   IF (T + 10 .GT. -DXPARG(1)) RETURN
   G1 = EXP(-T)
   H2 = H6*H6
   H7 = H2*H6
   H5 = 2*G1
   H4 = G1
   N = 1
   V1 = 1.5D0
   S1 = H5*H7/V1
   T = 2*T
   J = 0
35  H7 = H2*H7
   H4 = (T*H5 - H4)/N
   H5 = (H4 - H5)/V1
   N = N + 1
   V1 = N + .5D0
   Z = H5*H7/V1
   S1 = S1 + Z
  
```

```
IF (ABS(Z) .GT. E*ABS(S1)) GOTO 35
  IF (J .GT. 0) GOTO 40
    J = 1
    GOTO 35
40  EQSIG = A4*G1*S1/2
    KKK = 17
    RETURN
  END
```

## SUBROUTINE ERF5(X,EXPP,Y)

```

C-----
C  Y = THE REAL ERROR FUNCTION OF X. EXPP = EXP(-X*X).
C  IF EXP(-X*X) NOT AVAILABLE SET EXPP .LT. 0.
C-----
      DIMENSION      A(4)  ,B(4)  ,P(8)  ,Q(8)  ,R(5)  ,S(5)
C-----
      DOUBLE PRECISION  A      ,AX      ,B      ,BOT      ,C      ,EXPP
      DOUBLE PRECISION  P      ,Q      ,R      ,S      ,T      ,TOP
      DOUBLE PRECISION  X      ,X2      ,Y
C-----
      DATA  C/.564189583547756D0/
      DATA  A(1)/-1.65581836870402D-4/,  A(2)/3.25324098357738D-2/,
*          A(3)/1.02201136918406D-1/,  A(4)/1.12837916709552D0/
      DATA  B(1)/4.64988945913179D-3/,  B(2)/7.01333417158511D-2/,
*          B(3)/4.23906732683201D-1/,  B(4)/1.00000000000000D0/
      DATA  P(1)/-1.36864857382717D-7/,  P(2)/5.64195517478974D-1/,
*          P(3)/7.21175825088309D0/,  P(4)/4.31622272220567D01/,
*          P(5)/1.52989285046940D02/,  P(6)/3.39320816734344D02/,
*          P(7)/4.51918953711873D02/,  P(8)/3.00459261020162D02/
      DATA  Q(1)/1.00000000000000D0/,  Q(2)/1.27827273196294D01/,
*          Q(3)/7.70001529352295D01/,  Q(4)/2.77585444743988D02/,
*          Q(5)/6.38980264465631D02/,  Q(6)/9.31354094850610D02/,
*          Q(7)/7.90950925327898D02/,  Q(8)/3.00459260956983D02/
      DATA  R(1)/2.10144126479064D0/,  R(2)/2.62370141675169D01/,
*          R(3)/2.13688200555087D01/,  R(4)/4.65807828718470D0/,
*          R(5)/2.82094791773523D-1/
      DATA  S(1)/9.41537750555460D01/,  S(2)/1.87114811799590D02/,
*          S(3)/9.90191814623914D01/,  S(4)/1.80124575948747D01/,
*          S(5)/1.00000600000000D0/
C-----
      AX = ABS(X)
      T = X*X
      IF (AX .GE. 0.5D0) GO TO 5
      TOP = ((A(1)*T + A(2))*T + A(3))*T + A(4)
      BOT = ((B(1)*T + B(2))*T + B(3))*T + B(4)
      Y = X*TOP/BOT
      RETURN
C
5 IF (AX .GT. 4.0D0) GO TO 10
      TOP = ((((((P(1)*AX + P(2))*AX + P(3))*AX + P(4))*AX + P(5))*AX
*          + P(6))*AX + P(7))*AX + P(8)
      BOT = ((((((Q(1)*AX + Q(2))*AX + Q(3))*AX + Q(4))*AX + Q(5))*AX
*          + Q(6))*AX + Q(7))*AX + Q(8)
      IF (EXPP .LT. 0.D0) EXPP = EXP(-T)
      Y = 0.5D0 + (0.5D0 - EXPP*TOP/BOT)
      IF (X .LT. 0.0D0) Y = -Y
      RETURN

```



```

10 Y = 1.0D0
  IF (AX .GE. 5.6D0) GO TO 15
  X2 = 1.0D0/T
  TOP = (((R(1)*X2 + R(2))*X2 + R(3))*X2 + R(4))*X2 + R(5)
  BOT = (((S(1)*X2 + S(2))*X2 + S(3))*X2 + S(4))*X2 + S(5)
  Y = (C - TOP/(T*BOT)) / AX
  IF (EXPP .LT. 0.D0) EXPP = EXP(-T)
  Y = 0.5D0 + (0.5D0 - EXPP*Y)
15 IF (X .LT. 0.0D0) Y = -Y
  RETURN
  END

```

DOUBLE PRECISION FUNCTION FN2(T5,IM,IL,R3,H,K,L,  
\* S1,S2,S3,HZ,DEP,J,D)

C-----  
C FN2 GIVES THE INTEGRAND OF ELLCOV. USED BY RQUAD,SQUAD,TQUAD1.  
C J = 0,1,2 SPECIFIES CIRC CV OR PKILL. DEP = -DEPSLN(0). D NEEDED  
C FOR CIRC CV. HZ = L\*SQRT(1/2)/S3. SEE BELOW FOR IM, IL.

C-----  
C U(J) ARE USED WHEN SQUAD CALLS FN2 AND THE INPUT INTEGRATION  
C LIMITS A,B ARE UNCHANGED FROM L-R AND L THEN R, USED IN PKILL  
C OR CIRC CV, IS GIVEN BY R3\*U(IM).  
C IF IL .NE. 0 COMPUTE FN2 USING THE U(J) USING INPUT IM.  
C IF IL .EQ. 0 COMPUTE FN2 USING T5 WITHOUT USING U(J).  
C U(I)= SQRT(1 - .25\*(1 + X(I)\*\*2), I = 12,...,1.  
C U(N+I)= SQRT(1 - .25\*(1 - X(I)\*\*2),  
C X(I) ARE THE GAUSSIAN ABSCISSAS OF ORDER 24. N = 12.

C-----	EXTERNAL	CIRC CV ,PKILL				
	DOUBLE PRECISION	K ,L ,U(24)				
C-----	DOUBLE PRECISION	C8 ,D ,DEP ,H ,HZ ,P				
	DOUBLE PRECISION	R ,R3 ,S1 ,S2 ,S3 ,T5				
	DOUBLE PRECISION	V2 ,XJ1				

C-----  
DATAU(12) /.6933245481114434D-1/, U(11) /.1584669762375325D0/,  
\* U(10) /.2465216831531283D0/, U(9) /.3322034239275342D0/,  
\* U(8) /.4146060693752110D0/, U(7) /.4929421360269080D0/,  
\* U(6) /.5665216929750006D0/, U(5) /.6347583153788445D0/,  
\* U(4) /.6971793487850529D0/, U(3) /.7534359213923792D0/,  
\* U(2) /.8033112478280709D0/, U(1) /.8467264801504051D0/,  
\* U(13) /.8837435290006371D0/, U(14) /.9145642833397272D0/,  
\* U(15) /.9395256076023404D0/, U(16) /.9590894389984678D0/,  
\* U(17) /.9738272897857341D0/, U(18) /.9843985374573839D0/,  
\* U(19) /.9915221334137353D0/, U(20) /.9959418550983111D0/,  
\* U(21) /.9983860184685972D0/, U(22) /.9995236326707759D0/,  
\* U(23) /.9999201660778605D0/, U(24) /.9999971046393888D0/

C-----  
DATA C8 /1.4142 13562 37310D0/  
C-----

FN2 = 0.D0  
IF (T5 .GT. 11.2D0) RETURN  
XJ1 = EXP(-T5\*T5)  
P = HZ - T5  
IF (IL .EQ. 0) GOTO 5  
R = R3\*U(IM)  
GOTO 10  
5 V2 = C8\*S3\*T5  
R = (R3 - L)\*(R3 + L) + V2\*(2\*L - V2)

```

IF(R .LT. 0.0D0) RETURN
R = SQRT(R)
10 IF (L .NE. 0.0D0) GO TO 15
   XJ1 = 2*XJ1
   GO TO 20
15  V2 = 4*HZ*P
   IF (V2 .GT. DEP) GO TO 20
   XJ1 = XJ1*((0.5D0 + EXP(-V2)) + 0.5D0)
C-----
20 IF (J .GT. 1) GO TO 25
   CALL CIRCVR(R/S1,D,J,P,IER)
   GO TO 30
25 CALL PKILL(R,S1,S2,H,K,P)
30 FN2 = XJ1*P
   RETURN
   END

```

```

SUBROUTINE HSEXP (X ,E, Y)
C-----
C          EVALUATION OF (EXP(X) - 1)/X
C
C          Y = (EXP(X) - 1)/X
C
C E IS AN INPUT/OUTPUT VARIABLE. IF E IS .GE. 0 THEN IT IS ASSUMED
C THAT E = EXP(X). IN THIS CASE E IS NOT MODIFIED. IF E IS NEGATIVE
C THEN E IS SET TO EXP(X) WHEN THIS VALUE IS NEEDED IN HSEXP.
C-----
C          DOUBLE PRECISION  X      ,P1   ,P2   ,Q1   ,Q2   ,Q3
C          DOUBLE PRECISION  Q4      ,E    ,Y
C-----
C          DATA  P1/ .914041914819518D-09/,    P2/ .238082361044469D-01/,
*              Q1/-.499999999085958D+00/,    Q2/ .107141568980644D+00/,
*              Q3/-.119041179760821D-01/,    Q4/ .595130811860248D-03/
C-----
C          IF (ABS(X) .GT. 0.15D0) GO TO 5
C          Y = ((P2*X + P1)*X + 1.0D0)/((((Q4*X + Q3)*X + Q2)*X
*              + Q1)*X + 1.0D0)
C          RETURN
C
5 IF (E .LE. 0.D0) E = EXP(X)
  IF (X .GT. 0.0D0) GO TO 10
  Y = ((E - 0.5D0) - 0.5D0)/X
  RETURN
10 Y = E*(0.5D0 + (0.5D0 - 1.0D0/E))/X
  RETURN
  END

```

SUBROUTINE RQUAD(A,B,XI1,M,N,X,Y,R3,H,K,L,S1,S2,S3,DEP,J,D)

C-----  
C RQUAD IS A QUADRATURE ROUTINE WHICH USES GAUSSIAN MULTIPLIERS  
C TO OBTAIN THE INTEGRAL C FROM A TO B OF FN2(T). A, B ARE THE  
C LOWER AND UPPER LIMITS OF INTEGRATION. OUTPUT IS XI1 = C.  
C INPUT IS M, NO. OF EQUAL SUBDIVISIONS OF [A,B] WITH SAME ORDER  
C GAUSSIAN INTEGRATION APPLIED ON EACH SUBDIVISION. M SET TO 1;  
C HIGHER VALUES OF M USED ONLY FOR CHECKING PURPOSES.  
C N, (2N = ORDER OF GAUSSIAN MULTIPLIERS USED). SET AT N = 12.  
C X(\*),Y(\*)--STORED VALUES OF GAUSSIAN ABSCISSAS AND MULTIPLIERS  
C ON (-1,1}. REMAINING ARGUMENTS OF THE CALL LINE ARE USED AS  
C INPUT PARAMETERS FOR FN2, (DEP = -DEPSLN(0)).  
C J = 0,1,2 FOR CIRC V OR PKILL. D NEEDED FOR CIRC V.  
C-----

	DIMENSION	X(1)	Y(1)				
	EXTERNAL	FN2					
C-----							
	DOUBLE PRECISION	FN2	,K	,L			
	DOUBLE PRECISION	A	,B	,C7	,D	,DEP	,D3
	DOUBLE PRECISION	D4	,E2	,F	,G	,H	,HZ
	DOUBLE PRECISION	R3	,S1	,S2	,S3	,T	,TM
	DOUBLE PRECISION	TM1	,TP	,TP1	,X	,XI1	,Y

C-----  
DATA C7/.7071067811865475D0/  
C-----

C-----  
HZ = C7\*L/S3  
5 G = 0.D0  
K1 = 0  
D3 = B - A  
D4 = D3/M  
D3 = D4/2  
E2 = A + D3  
10 K1 = K1 + 1  
HZ = C7\*L/S3  
C-----

C START GAUSSIAN INTEGRATION.  
C-----

I = N + 1  
15 I = I - 1  
T = D3\*X(I)  
TM1 = -T + E2  
TM = FN2(TM1,I,0,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)  
TP1 = T + E2  
TP = FN2(TP1,I,0,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)  
F = Y(I)\*(TM + TP)  
G = G + F

```
IF (I .GT. 1) GOTO 15
E2 = E2 + D4
IF (K1 .NE. M) GOTO 10
XI1 = D3*G
RETURN
END
```

SUBROUTINE SEQHZ3(R,L,S1,S3,EPS,DEP,XK0,AA,EQS,SEQ,KKK)

C-----  
C SEQ GIVES THE TRIVARIATE NORMAL PROBABILITY (ELLCOV) OVER  
C A SPHERE WITH CENTER (0,0,L) AND RADIUS R. THE NORMAL DIST-  
C TRIBUTION HAS CORRESPONDING STANDARD DEVIATIONS S1 = S2, S3.  
C  $XK0 = (L)**2$ .  $AA = \exp(-((L-R)/(\sqrt{2}*\max(S1,S3))**2))$ .  
C  $EQS = P$  FOR EQUAL SIGMAS ( $S1 = S3$ ). KKK IDENTIFIES PATHS,  
C USED FOR EASE IN FOLLOWING PROGRAM.  $EPS = 10*DPMPAR(1)$ .  
C-----

C S1 = S2 AND H = K = 0.  
C-----

EXTERNAL	AERF	,BDAW1	,DAW	,DXDAW	,DXPARG
EXTERNAL	ERF	,ERFCR	,ERFC0	,HSEXP	,EQSIG

DOUBLE PRECISION	AERF	,BDAW1	,DAW	,DXDAW
DOUBLE PRECISION	DXPARG	,ERF	,ERFCR	,EQSIG

DOUBLE PRECISION L

DOUBLE PRECISION	AA	,B1	,C5	,C7	,DEP	,E
DOUBLE PRECISION	EPS	,EQS	,ERL	,ET	,E1	,F1
DOUBLE PRECISION	R	,S	,SEQ	,S0	,S1	,S3
DOUBLE PRECISION	T	,T0	,T1	,T3	,U	,U0
DOUBLE PRECISION	U1	,U2	,V1	,V2	,V3	,V4
DOUBLE PRECISION	W9	,X	,XK0	,XL1	,XL2	,X2
DOUBLE PRECISION	Y	,Y1	,Y2	,Z	,ZL	,ZL1
DOUBLE PRECISION	ZM	,ZMN	,ZP	,ZPN	,ZR	,ZR1
DOUBLE PRECISION	Z1					

DATA B1 /.56418 95835 47756D0/, C7/.70710 67811 86548D0/  
DATA C5 /11.2D0/

E = MAX (EPS/2,1D-10)  
E1 = 2D1\*EPS  
SEQ = 0.D0  
ZL = L\*C7/S3  
ZR = R\*C7/S3  
Y1 = 4\*ZL\*ZR  
X2 = ZR\*ZR  
V1 = R\*R/(S1\*S1)

ZL = L/(SQRT(2)\*S3) ZR = R/(SQRT(2)\*S3) V1 = R\*R/(S1\*S1)

IF (Y1 .GT. 1.D1) GOTO 15  
IF (X2 .GT. 2.D0) GOTO 15  
IF (V1 .GT. 2.D0) GOTO 15

```

C-----
C  4*ZL*ZR .LE. 10,   ZR*ZR .LE. 2,   V1 .LE. 2.
C-----
      F1 = EXP(-ZL*ZL/2)
      S = .66666 66666 666667D0*F1
      T = S
      Y = 2*F1
      Z = .5D0*Y1
      Y1 = Y1*F1
      Z1 = 2*X2
      J = 0
      K = 1
5      K = K + 1
      Y = (Z*Y1 - Z1*Y)/K
      K = K + 1
      Y1 = (Z*Y - Z1*Y1)/K
      T = (Y/K - V1*T)/(K + 2)
      S = S + T
      IF (ABS(T) .GT. E*ABS(S)) GOTO 5
      IF (J .NE. 0) GOTO 10
      J = 1
      GOTO 5
10     SEQ = B1*ZR*V1*S*F1
      KKK = 1
      RETURN
C-----
C  EITHER  4*ZL*ZR .GT. 10 .OR. ZR*ZR .GT. 2 .OR. V1 .GT. 2.
C-----
15     ZM = C7*(L - R)/S3
      KKK = 0
      IF (ZM .GT. C5) RETURN
      V2 = S3*S3/(S1*S1)
      XL1 = ABS(.5D0 + (.5D0 - V2))
      IF (S3 .LT. S1) AA = EXP(-ZM*ZM)
      IF (XL1 .GT. E) GOTO 20
      SEQ = EQS
C-----
C      XK0 = L*L
C-----
      KKK = 4
      IF (R .GT. L) RETURN
      SEQ = EQSIG(R,XK0,L,S3,E1,DEP,AA)
      RETURN
20     XL2 = SQRT(XL1)
      JJJ = -1
      IF (S1 .LT. S3) JJJ = 1
25     Z = ZR*ZR*XL1
      IF (ZL .NE. 0.D0 .OR. Z .GT. 3D0 ) GOTO 40

```



```

C-----
C  L.EQ. 0 AND  R*C7/S3)**2*(ABS(1-(S3/S1)**2)).LE. 3
C-----
      K = 3
      JJ = -2*JJJ
      S = JJ*Z/3
      T = S
30   K = K + 2
      T = JJ*Z*T/K
      S = S + T
      IF (ABS(T) .GT. E*ABS(S)) GOTO 30
      IF (S3 .GT. S1) GOTO 35
      EQS = EQSIG(R,XK0,L,S3,E1,DEP,AA)
35   SEQ = EQS - 2*ZR*B1*AA*S
      KKK = 5
      RETURN
C-----
C  L.NE. 0 OR  R*C7/S3)**2*(ABS(1-(S3/S1)**2)).GT. 3
C-----
40   Y = C7*(L - R + V2*R)/S3
      Y2 = C7*(L + R - V2*R)/S3
      IF (V2 .LE. 1.D0) GOTO 45
      T = Y
      Y = Y2
      Y2 = T
45   S0 = Y/XL2
      F1 = Y2/XL2
      IF (V2 .GT. 1D-2 .OR. V2*MAX(ZL,ZR) .GT. .5D0) GOTO 65
C-----
C  S3/S1 .LE. .1D0 .AND. MAX(ZL,ZR)*(S3/S1)**2 .LE. 1/2.
C-----
      X = (R - L)*(R + L)/(2*S1*S1)
      T0 = 0.D0
      IF (ZM .GT. 10.5D0) GOTO 60
      T0 = AERF(ZL,ZR)
      ET = EXP(-X)
      IF (ET .EQ. 0.D0) GOTO 60
C-----
C  HSEXP COMPUTES (EXP(X)-1)/X
C-----
      CALL HSEXP(-X,ET,SEQ)
      SEQ = X*SEQ*T0
C-----
C  AA = EXP(-((L-R)*C7/S3)**2)
C-----
      ERL = 0.D0
      ZPN = 0.D0

```

```

T1 = B1*AA
T3 = T1
IF (Y1 .GT. -DXPARG(1)) GOTO 50
ERL = EXP(-Y1)
CALL HSEXP(-Y1,ERL,T1)
T1 = T3*Y1*T1
ZPN = 1.D0
50  U0 = 1.D0
    V3 = 2*V2
    U1 = -V3*ZL
    S = T1*U1
    ZP = ZL + ZR
    ZPN = 1.D0
    ZMN = 1.D0
    N = 1
C-----
55  N = N + 1
    IF (N .GT. 20) GOTO 65
    ZPN = ZPN*ZP/N
    ZMN = ZMN*ZM/N
    T0 = .5D0*T0/N + T3*(ZMN - ERL*ZPN)
    U2 = V3*(-ZL*U1 + (N - 1)*U0)
    V4 = T0*U2
    U0 = U1
    U1 = U2
    N = N + 1
    ZPN = ZPN*ZP/N
    ZMN = ZMN*ZM/N
    T1 = .5D0*T1/N + T3*(ZMN - ERL*ZPN)
    U2 = V3*(-ZL*U1 + (N - 1)*U0)
    V4 = V4 + U2*T1
    S = S + V4
    U0 = U1
    U1 = U2
    IF (ABS(V4) .GT. ABS(SEQ - ET*S)*E) GOTO 55
    SEQ = (SEQ - ET*S)/2
    KKK = 2
    RETURN
60  SEQ = T0/2
    KKK = 3
    RETURN
C-----
C  V2=(S3/S1)**2 .GT. 1D-2 .OR. V2*MAX(ZL,ZR) .GT. .5D0)
C-----
65  IF (S0 .LT. 5D0) GOTO 85
    Z1 = B1*ZR*XL1
    W9 = EXP(-Y1)

```

```

CALL HSEXP(-Y1,W9,T)
Z = 4*Z*T - JJJ*(1 + W9)
U = AA/(2*Y*Y2)
IF (R .GT. L .AND. S3 .GT. S1) GOTO 70
EQS = EQSIG(R,XK0,L,S3,E1,DEP,AA)
70 IF (JJJ .GT. 0) GOTO 80
ZL1 = 0.D0
IF (W9 .EQ. 0.D0) GOTO 75
ZL1 = Y*ERFCR(F1)
75 SEQ = EQS - U*(Z1*Z - Y2*ERFCR(S0) + W9*ZL1)
KKK = 6
RETURN
80 SEQ = EQS - B1*U*XL1*(ZR*Z + BDAW1(Y,Y2,XL2,W9))
KKK = 7
RETURN
C-----
C   USE (13) - (15) OF REPORT 87-27
C-----
85 SEQ = AERF(ZL,ZR)
ZL1 = ZL/XL2
ZR1 = XL2*ZR
J = -5
IF (JJJ .GT. 0) GOTO 110
IF (L .EQ. 0D0) GOTO 105
90 IF (S0 .LE. 0.D0) GOTO 100
W9 = EXP(-Y1)
Y = -1.D0
Y2 = 0.D0
CALL ERFC0(1,S0,Y,Y1)
IF (W9 .EQ. 0.D0) GOTO 95
CALL ERFC0(1,F1,Y,Y2)
95 SEQ = .5D0*(SEQ - AA/XL2*(Y1 - W9*Y2))
KKK = 8
RETURN
100 X2 = AERF(ZL1,ZR1)
SEQ = .5D0*(SEQ - X2*EXP(-.5D0*(R*R - L*L/XL1)/(S1*S1))/XL2)
KKK = 9
RETURN
105 SEQ = SEQ/2 - EXP(-V1/2)*ERF(ZR*XL2)/XL2
KKK = 10
RETURN
C-----
C   S1 .LT. S3---USE (16) OF REPORT 87-27
C-----
110 J = -6
IF (J .EQ. 0D0) GOTO 120
Y = 0.D0

```

```
W9 = EXP(-Y1)
IF (W9 .EQ. 0.D0) GOTO 115
Y = DAW(S0)
115 SEQ = 0.5D0*SEQ - B1*AA/XL2*(DAW(F1) - W9*Y)
   KKK = 11
   RETURN
120 SEQ = .5D0*SEQ - 2*B1*AA*ZR*DXDAW(ZR*XL2)
   KKK = 12
   RETURN
END
```

SUBROUTINE SQUAD(A,B,Z1,N,X,Y,R3,H,K,L,S1,S2,S3,EPS,DEP,  
\* J,D,PY,IL)

C-----  
C SQUAD IS A QUADRATURE ROUTINE WHICH USES GAUSSIAN MULTIPLIERS  
C OF ORDER (24) FOR AN ESTIMATE OF THE INTEGRAL Z1 FROM A TO B  
C OF FN2(T). A, B ARE THE LOWER AND UPPER LIMITS OF INTEGRATION.  
C THE OUTPUT ARE A, B, Z1, WHERE A,B MAY HAVE NEW VALUES, SUCH  
C THAT FN2 IS NEGLIGIBLE ON (A,A(NEW)), AND (B(NEW),B), THAT IS  
C WHEN FN2(T) .LT. 1E-8\*MIN(MAX(G, PY, FA, FB), 1/2).  
C EPS = 10\*DPMPAR(1). DEP = - DEPSLN(0). IL IS INFO PARAMETER.  
C J = 0,1,2 SPECIFIES CIRC V OR PKILL. CIRC V NEEDS D IN FN2.

C-----	DIMENSION	X(1)	Y(1)	TM(24)		
	EXTERNAL	FN2				
	DOUBLE PRECISION	DEP	FN2	K	L	
C-----						
	DOUBLE PRECISION	A	B	B1	C7	D
	DOUBLE PRECISION	EPS	E3	FA	FB	G
	DOUBLE PRECISION	HZ	PY	RZ	R3	S1
	DOUBLE PRECISION	S3	TM	TM1	X	Y
	DOUBLE PRECISION	Z1	Z2			ZT

C-----  
DATA B1 /.5641895835477563D0/, C7/.7071067811865475D0/  
C-----

```

IL = 0
ZT = 0
FA = 0.D0
G = 0.D0
NT = 2*N
RZ = C7*R3/S3
HZ = C7*L/S3
IF (ABS(HZ - B) .GT. EPS*HZ) GOTO 5
Z2 = HZ - RZ
IF (ABS(Z2 - A) .LE. EPS*ABS(Z2)) IL = 1
5  E3 = (B - A)/2
   D1 = (B + A)/2
   J1 = 0
   I = N + 1
10  I = I - 1
   J1 = J1 + 1
   Z2 = E3*X(I)
   TM1 = -Z2 + D1
   TM(J1) = Y(I)*FN2(TM1,I,IL,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)
   TM1 = Z2 + D1
   M = I + N

```

```

      TM(M) = Y(I)*FN2(TM1,M,IL,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)
      G = G + (TM(J1) + TM(M))
      IF (I .GT. 1) GOTO 10
      IF (IL .EQ. 0) FA = FN2(A,I,0,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)
      FB = FN2(B,M,0,R3,H,K,L,S1,S2,S3,HZ,DEP,J,D)
      Z1 = E3*B1*G
      IF (Z1 + PY .LT. 1D-37) RETURN
      ZT = 1D-8*MIN(MAX(G,PY,FA,FB),.5D0)
      IF (FA .GT. ZT) GOTO 25

```

```

C-----
C   ATTEMPT TO FIND LARGER A
C-----

```

```

      II = 0
15      II = II + 1
          IF (TM(II) .GT. ZT) GOTO 20
          IF (II .LT. NT) GOTO 15
      Z1 = 0D0
      RETURN
20      IF (II .EQ. 1) GOTO 25
      I = II - N - 2
      IF (I .GE. 0) I = I + 1
      JJ = IABS(I)
      A = ISIGN(1,I)*E3*X(JJ) + D1
25      IF (FB .GT. ZT) RETURN

```

```

C-----
C   ATTEMPT TO FIND SMALLER B
C-----

```

```

      II = NT + 1
30      II = II - 1
          IF (TM(II) .GT. ZT) GOTO 35
          IF (II .GT. 1) GOTO 30
35      IF (II .EQ. NT) RETURN
      I = II - N + 1
      IF (I .LE. 0) I = I - 1
      JJ = IABS(I)
      B = ISIGN(1,I)*E3*X(JJ) + D1
      RETURN
      END

```

SUBROUTINE TQUA1(A,B,N,X,R3,H,K,L,S1,S2,S3,PY,T8,DEP,F)

C-----  
C TQUA1 IS A ROUTINE THAT FINDS THE SMALLEST VALUE OF T, SAY,C ON  
C (A,T1,...,Tk,...,B) FOR WHICH FN2(T) .GE. T8, AND LARGEST VALUE  
C SAY C1, FOR WHICH STARTING FROM B IN DECREASING T, FN2(C1) .GE.  
C T8, WHERE T8 = MAX(1D2\*DPMPAR(2),1D-42).  
C TI = ISIGN(1,I)\*E3\*X(ABS(I)) + D3,  
C WITH X(I) THE GAUSSIAN ABSCISSAS OF ORDER 2\*N, E3 = (B - A)/2,  
C AND D3 = (B + A)/2, X's = GAUSSIAN ABSCISSAS OF O(24) USED.  
C IF C=T(L+1) AND C1=T(K-1), THE OUTPUT A=T(L) AND B=T(K) AND  
C F = FN2(T(L)). DEP = -DEPSLN(0).  
C-----

DIMENSION	X(1)		
EXTERNAL	FN2		
DOUBLE PRECISION	FN2	,K	,L

C-----  

DOUBLE PRECISION	A	,B	,C7	,D	,DEP	,D3
DOUBLE PRECISION	E3	,F	,H	,HZ	,PY	,R3
DOUBLE PRECISION	S1	,S11	,S2	,S22	,S3	,TM
DOUBLE PRECISION	TM1	,T8	,T9	,X		

C-----

DATA C7/.7071067811865475D0/  
C-----

D = 0.D0  
HZ = C7\*L/S3  
S11 = S1  
S22 = S2  
J = 2  
TM1 = A  
TM = 0.D0  
IF (S1 .NE. S2) GOTO 5  
J = 1  
D = SQRT(H\*H + K\*K)/S1  
GOTO 15  
5 IF (H + K .NE. 0.D0) GOTO 15  
J = 0  
IF (S1 .GT. S2) GOTO 10  
D = S11  
S11 = S22  
S22 = D  
10 D = S22/S11  
15 NT = 2\*N + 1  
E3 = (B - A)/2  
D3 = (B + A)/2  
T9 = T8  
IF (PY .GT. 0D0) T9 = MIN(T8,PY)

```

DO 20 II = 1, NT
  I = II - 13
  IF (I .EQ. 0) GOTO 20
  A = TM1
  F = TM
  JJ=IABS(I)
  TM1 = ISIGN(1,I)*E3*X(JJ) + D3
  TM = FN2(TM1,I,0,R3,H,K,L,S11,S22,S3,HZ,DEP,J,D)
  IF (TM .GT. T9) GOTO 25
20  CONTINUE
25  TM1 = B
  DO 30 II = 1, NT
    I = II - 13
    IF (I .EQ. 0) GOTO 30
    B = TM1
    JJ = IABS(I)
    TM1 = -ISIGN(1,I)*E3*X(JJ) + D3
    IF (TM1 .LE. A) GOTO 35
    TM = FN2(TM1,I,0,R3,H,K,L,S11,S22,S3,HZ,DEP,J,D)
    IF (TM .GT. T9) GOTO 35
30  CONTINUE
35  IF (TM1 .LE. A) B = A
    RETURN
  END

```



**APPENDIX C**

**FORTRAN LISTINGS FOR ELINV3 AND SUPPORTING ROUTINES**

**FORTRAN LISTINGS FOR ELINV3 AND SUPPORTING ROUTINES**

Below we give a summary of the various subprograms that are used for computing  $\tilde{R}$ . These subprograms are listed in this appendix, except for those which are contained in NSWCLIB [13]. The NSWCLIB routines are identified below with a superscript \*. All subprograms are given in double precision.

**REFERENCING OF ROUTINES USED TO COMPUTE  $\tilde{R}$** 

ELINV3	uses:	DPMPAR*	ELLCOV	ELLRC	GAMINV*	SUB3
ELLRC	uses:	AERF*	DEPSLN*	DPMPAR*	FCN1	
FCN1	uses:	AERF*				
SUB3	uses:	ELLCOV				

SUBROUTINE ELINV3(P3,HX,HY,HZ,SX,SY,SZ,R,PXD,IND,NN)

C-----  
C (X,Y,Z) IS A POINT IN A CARTESIAN COORDINATE SYSTEM. ELINV3  
C RETURNS R, THE RADIUS OF THE SPHERE WITH CENTER (HX,HY,HZ) WHICH  
C HOLDS P3 OF THE NORMAL ELLIPSOIDAL DISTRIBUTION WITH MEAN (0,0,0)  
C AND STANDARD DEVIATIONS SX, SY, SZ IN X,Y,Z DIRECTIONS, RESPECT-  
C IVELY. ESTIMATES OF P3, FOR A GIVEN R, P(R), ARE OBTAINED FROM  
C ELLCOV. R IS GENERALLY CORRECT TO AT LEAST 6 SIGNIFICANT DIGITS.  
C LET E2 = 10\*DPMPAR(1). THE INPUT P3 SHOULD SATISFY 1D-20 .LE. P3  
C .LE. MIN(1 - E2, .99999999). IF P3 IS IN (0,1), AND THE ABOVE  
C INEQUALITIES ARE NOT SATISFIED, OUTPUT R MAY NOT BE CORRECT TO 6  
C SIGNIFICANT DIGITS. IND = -1, IF P3 .LT. MAX(1D-40, 1E6\*DPMPAR(2)),  
C P3 .NE. 0. IND = 1, IF P3 .GT. 1 - MAX(1D-12, E2); R SET TO -1D10, IF  
C ABS(IND) = 1. NN = THE NO. OF ITERATIONS USED; NN .LE. 30, NN  
C AVERAGES 6. IND = 2, IF NN = 30. LET RH AND RL DENOTE THE  
C CURRENT UPPER AND LOWER BOUNDS FOR R. IND = 3 IF (RH - RL) .LE.  
C MAX(E2, 1D-14)\*R AND ABS(P(R) - P3) .GT. MAX(E2, 1E-8)\*P3; THE  
C PRECISION OF THE MACHINE IS NOT ADEQUATE TO REVERSE THE LAST  
C INEQUALITY. IF IND = 4, THE VALUE OF R IS ACCEPTABLE BUT ELLCOV  
C CANNOT BE COMPUTED WITH SUFFICIENT ACCURACY TO DETERMINE R WITH  
C FULL ACCURACY.  
C REF: INTEGRATION OF THE TRIVARIATE NORMAL DISTRIBUTION OVER AN  
C OFFSET SPHERE AND AN INVERSE PROBLEM. NSWC TR. 87-27, 2/1988.  
C REF: SIGNIFICANT DIGIT COMPUTATION OF THE ELLIPSOIDAL COVERAGE  
C FUNCTION AND ITS INVERSE. NAVSWC TR 91-487.

C-----  

DIMENSION	A6(17)	B6(17)				
EXTERNAL	DPMPAR	,ELLCOV	,ELLRC	,GAMINV	,SUB3	

C-----  

DOUBLE PRECISION	DPMPAR	,ELLCOV	,ELLRC		
------------------	--------	---------	--------	--	--

C-----  

DOUBLE PRECISION	A6	,B6	,C1	,C3	,C4	,D3
DOUBLE PRECISION	D4	,D5	,E1	,E2	,E3	,E4
DOUBLE PRECISION	E5	,E6	,E8	,F0	,F1	,GX
DOUBLE PRECISION	GY	,GZ	,HX	,HY	,HZ	,PH
DOUBLE PRECISION	PHD	,PL	,PLD	,PX	,PXD	,PXDO
DOUBLE PRECISION	P3	,R	,RH	,RL	,RF	,R1
DOUBLE PRECISION	R2	,S	,SX	,SY	,SZ	,V4
DOUBLE PRECISION	V5	,WX	,WY	,WZ	,W2	,W4
DOUBLE PRECISION	XK0	,XK2	,XM0	,X0	,X1	,XGAMIN

C-----  
DATA A6(1)/1D-30/A6(2)/1D-25/A6(3)/1D-20/A6(4)/1D-15/A6(5)/1D-10/  
+ A6(6)/1D-8/A6(7)/5D-6/A6(8)/1D-4/A6(9)/1D-2/A6(10)/1D-1/  
+ A6(11)/3D-1/A6(12)/0.6D0/A6(13)/0.9D0/A6(14)/0.999D0/  
+ A6(15)/.999999D0/A6(16)/.99999999D0/A6(17)/1.0D0/  
C-----

```

DATA B6(1)/1.56D-10/B6(2)/7.23D-9/B6(3)/3.36D-7/B6(4)/1.56D-5/
+ B6(5)/7.22D-4/B6(6)/3.36D-3/B6(7)/2.66D-2/B6(8)/7.23D-2/
+ B6(9)/3.39D-1/B6(10)/.765D0/B6(11)/1.1933D0/B6(12)/1.717D0/
+ B6(13)/2.5005D0/B6(14)/4.0335D0/B6(15)/5.538D0/B6(16)/
+ 6.35D0/B6(17)/7.7D0/
C-----
DATA C4/1D-20/C3/0.797884560802865D0/C1/.5773502691896258D0/
C-----
C C3 = SQRT(2/PI), C1 = 1/SQRT(3)
C-----
CT R,RL,RH,NN,PX,X0,X1,F1,PXD,F0
IND = 0
R = 0D0
IF (P3 .EQ. 0.0D0) RETURN
PXDO = -10D0
XK0 = HX*HX + HY*HY + HZ*HZ
XK2 = SQRT(XK0)
S = MAX(SX,SY,SZ)
E1 = 1D6*DPMPAR(2)
E2 = 10*DPMPAR(1)
E3 = MAX(E2,5D-9)
E4 = MAX(E2,1D-14)
E5 = MAX(E1,C4*C4)
E6 = MAX(E2,1D-8)*P3
W4 = SX*SX + SY*SY + SZ*SZ
R = -1D10
IF (P3 .LT. E5) GOTO 175
IF (P3 .GT. 1.0D0 - MAX(1D-12,E2)) GOTO 180
C-----
NN = 0
E8 = E6
IF (P3 .LT. 0.999D0) GOTO 5
E8 = MAX(E2, 1.0D-9)
IF (P3 .LT. 0.999999D0) GOTO 5
E8 = MAX(E2, 1.D-10)
IF (P3 .LT. 0.99999999D0) GOTO 5
E8 = MAX(E2,1D-11)
C-----
C FIRST ESTIMATE FOR RMIN
C-----
5 PL = P3*S/C3
RL = MAX(3.0D0*P3*SX*SY*SZ/C3, PL*PL*PL)
IF (P3 .GE. 0.5D0) GOTO 10
R = RL**(1.D0/3.D0)
GOTO 15
10 R = XK2
IF (RL .GT. XK0*XK2) R=RL**(1.D0/3.D0)

```

```

15  RL = R
    PL = 0D0
    PLD = - P3

```

```

C-----
C  FIRST ESTIMATE FOR RMAX
C-----

```

```

    DO 20 J = 1, 17
      IF (P3 .LE. A6(J)) GOTO 25
20  CONTINUE
25  R = XK2 + B6(J)*S
    RH = R
    PH = 1D0
    PHD = 1D0 - P3

```

```

C-----
C  GRUBB'S ESTIMATE FOR R
C-----

```

```

    KG = 0
    XM0 = 1.0D0 + XK0/W4
    WX = SX*SX/W4
    WY = SY*SY/W4
    WZ = SZ*SZ/W4
    GX = HX/SX
    GY = HY/SY
    GZ = HZ/SZ
    V4 = 2.0D0*(WX*WX*(1.0D0 + 2.0D0*GX*GX) + WY*WY*(1.0D0 + 2.0D0*
+    GY*GY) + WZ*WZ*(1.0D0 + 2.0D0*GZ*GZ))
    V5 = 8.0D0*(WX*WX*WX*(1.0D0 + 3.0D0*GX*GX) + WY*WY*WY
+    *(1.0D0 + 3.0D0*GY*GY) + WZ*WZ*WZ*(1.0D0 + 3.0D0*GZ*GZ))
    W2 = 0.5D0*V5/V4
    V5 = V5*V5/(V4*V4*V4)

```

```

C-----
    I2 = 0
    D3 = 1.1D0
    IF (P3 .LE. 0.8D0) GOTO 30
    D3 = 1.25D0
    IF (P3 .LE. 0.9D0) GOTO 30
    D3 = 1.9D0
30  D4 = P3
    PX = P3

```

```

C-----
35  RP = R
    IF (PX .EQ. 1.D0) PX = 1.D0 - E8
    CALL GAMINV(4.D0/V5, XGAMIN, 0.D0, PX, 1.D0 - PX, IERR)
    R = W4*((XGAMIN - 4.0D0/V5)*W2 + XM0)
    IF (R .LE. RL*RL .OR. R .GE. RH*RH) GOTO 75
    R = SQRT(R)
    IF (KG .EQ. 0) GOTO 40
    IF (ABS(R - RP) .LT. E3*R) GOTO 75

```

```

40 CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
   KG = 1
45 IF (ABS(PXD) .LE. E8) RETURN
   IF (PXD .LT. 0.D0) GOTO 60
C-----
C      PX .GE. P3
C-----
      IF (I2 .LT. 0) GOTO 100
      IF (NN .GT. 4) GOTO 75
      IF (PX .GT. 10.0D0*P3) GOTO 75
      IF (P3 .GT. 0.01D0 .OR. PX .EQ. 1.0D0) GOTO 50
      IF (ABS(PXD) .GT. 0.1D0*P3) GOTO 50
      PX = P3 - 2.0D0*PXD
      D4 = P3 - 2.0D0*PXD
      GOTO 55
50 PX = D4**D3
   D4 = PX
55 I2 = 1
   GOTO 35
C-----
C      PX .LT. P3
C-----
60 D5 = 2.0D0 - D3
   IF (I2 .GT. 0) GOTO 100
   IF (NN .GT. 6 .OR. PX .LT. 0.01D0*P3) GOTO 75
   IF (P3 .GT. 0.01D0 .OR. PX .EQ. 0.5D0) GOTO 65
   IF (ABS(PXD) .GT. 0.1D0*P3) GOTO 65
   PX = P3 - 2.0D0*PXD
   D4 = P3 - 2.0D0*PXD
   GOTO 70
65 PX = D4**D5
   D4 = PX
70 I2 = -1
   GOTO 35
C-----
C      ESTIMATE FOR R USING CIRCUMSCRIBED CUBE. C1 = 1/SQRT(3).
C-----
75 R2 = ELLRC(HX,HY,HZ,SX,SY,SZ,P3,C1*RL,RH,E8,N6)
80 IF (R2 .LE. RL) GOTO 85
   RP = R2
   R = R2
C-----
C      COMPUTES ELLCOV(R) AND MAKES PROPER STORAGES
C-----
      CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
      IF (ABS(PXD) .LE. E8) RETURN

```

```

85  R1 = R2/C1
    IF (R1 .LT. RH) RH = R1
    IF ((P3 .LE. 0.2D0) .AND. (R2 .EQ. RP)) GOTO 95
90  RP = R
    R = 0.5D0*(RL + RH)
    IF (PL .EQ. 0D0 .OR. PH .GT. 1D4*PL) R = (RH + 3*RL)/4
    IF (ABS(RH - RL) .LE. E4*RL) GOTO 190
C-----
    CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
95  IF (ABS(PXD) .LE. E8) RETURN
    IF (ABS(RH - RL) .GT. 1D0*R) GOTO 90
    IF (ABS(R - RP) .GT. 5.D-3*R
+      .OR. ABS(PH - PL) .GT. 1.D-3*P3) GOTO 105
100 RP = R
    R = RL - (RL - RH)/(PL - PH)*PLD
    GOTO 110
105 RP = R
    R = 0.5D0*(RL + RH)
C-----
110 CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
    IF (ABS(PXD).GT. E8) GOTO 115
    R = R - (RL - RH)/(PL - PH)*PXD
    RETURN
115 IF (ABS(RH - RL) .LE. E4*R) GOTO 190
    DO 120 J2 = 1,25
        R = 0.5D0*(RL + RH)
        IF (PL .EQ. 0D0 .OR. PH .GT. 1D4*P3) R = (RH + 3*RL)/4
        CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+          ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
        IF (ABS(PXD).LT. E8) RETURN
        IF (ABS(RH - RL) .LE. E4*R) GOTO 190
        IF (PL .GT. 1D-3*PH) GOTO 125
120  IF (NN .GT. 30) GOTO 185
C-----
125 IK = 0
    IF (PL .EQ. 0D0) CALL SUB3(P3,RL,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
    IF (PH .EQ. 1D0) CALL SUB3(P3,RH,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
+      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
    IF (P3 .GT. .5D0) GOTO 130
C-----
C    P3 .LE. .5
C-----
    X1 = RL
    X0 = RH
    F0 = PHD

```

```

      F1 = PLD
      GOTO 135
C-----
C      P3 .GT. .5
C-----
130  X0 = RL
      X1 = RH
      F0 = PLD
      F1 = PHD
135  IF (ABS(RH - RL) .GT. 5.D-3*R .OR. ABS(PH - PL) .GT. 1D-3*P3)
      *   GOTO 145
140  R = 0.5D0*(RL + RH)
      GOTO 150
C-----
C      MODIFIED KING'S PROCEDURE
C-----
145  R = X1 - F1*(X1 - X0)/(F1 - F0)
      IF (IK .NE. 0) RETURN
150  CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
      +      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
      IF (KK .NE. 0) GOTO 195
      IF (ABS(PXD) .LE. E8) IK = 1
      IF (RH - RL .LT. E4*R) GOTO 190
      IF (NN .GE. 30) GOTO 185
      IF (ABS(PXD - PXDO) .GT. E8) GOTO 155
      IF (IK .NE. 0) GOTO 155
      IF (ABS(PXD) .GT. 1D2*E8) GOTO 155
      RETURN
155  PXDO = PXD
      IF (PXD*F1 .GT. 0.D0) GOTO 160
      D4 = X1
      X1 = X0
      X0 = D4
      D4 = F1
      F1 = F0
      F0 = D4
C-----
160  D3 = F1/(F1 + PXD)
      F0 = F0*D3
      X1 = R
      F1 = PXD
165  R = X1 - F1*(X1 - X0)/(F1 - F0)
      IF (IK .NE. 0) RETURN
      CALL SUB3(P3,R,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S
      +      ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)
      IF (KK .NE. 0) GOTO 195
      IF (ABS(PXD) .LE. E8) IK = 1
      IF (RH - RL .LT. E4*R) GOTO 190

```



```

      IF (NN .GE. 30) GOTO 185
      IF (ABS(PXD - PXDO) .GT. E8) GOTO 170
      IF (IK .NE. 0) GOTO 170
      IF (ABS(PXD) .GT. 1D2*E8) GOTO 170
      RETURN
170  PXDO = PXD
      IF (PXD*F1 .GT. 0.D0) GOTO 160
      X0 = X1
      F0 = F1
      F1 = PXD
      X1 = R
      GOTO 145
C-----
C    EXITS
C-----
C  P3 .LT. MAX(1D-40,1D6*DPMPAR(2)), IND = -1, R = -1E10.
C-----
175  IND = -1
      RETURN
C-----
C  P3 .GT. 1 - MAX(1D-12,10*DPMPAR(1)), IND = 1, R = -1E10.
C-----
180  IND = 1
      RETURN
C-----
C    NN .EQ. 30
C-----
185  IND = 2
      RETURN
C-----
C  RH - RL .LT. E4*R
C-----
190  IND = 3
      RETURN
C-----
C  ACCURACY LIMITED IN ELLCOV
C-----
195  IND = 4
      RETURN
C-----
      END

```

```

FUNCTION ELLRC(H,HK,HL,S1,S2,S3,P3,RMIN,RMAX,E8,N6)
C-----
C      2*ELLRC = LENGTH OF A SIDE OF A CUBE CENTERED AT (H,HK,HL) THAT
C      CONTAINS THE TRIVARIATE NORMAL PROBABILITY CONTENT P3 WITH (0,0
C      ,0) MEAN AND STANDARD DEVIATIONS (S1,S2,S3). IF N6 = 40, RESULT
C      SUSPECT. RMIN AND RMAX ARE INITIAL UPPER AND LOWER BOUNDS FOR
C      ELLRC. EXIT MADE WHEN LATEST ITERATE FOR ELLRC, F, SATISFIES
C      ABS(F - P3) .LT. E8*P3. E8 SET IN ELINV3.
C-----
      EXTERNAL      AERF ,DEPSLN ,DPMPAR ,FCN1
C-----
      DOUBLE PRECISION  AERF ,DEPSLN ,DPMPAR ,ELLRC
      DOUBLE PRECISION  A(3) ,RA(3) ,T(3) ,U(3)
C-----
      DOUBLE PRECISION  B1 ,C ,E ,EPS ,E1 ,E2
      DOUBLE PRECISION  E8 ,F ,H ,HK ,HL ,P3
      DOUBLE PRECISION  RMAX ,RMIN ,R0 ,R1 ,SQ ,SQPI
      DOUBLE PRECISION  S1 ,S2 ,S3 ,T1 ,T2 ,V1
C-----
      SQ = 1.414213562373095D0
      SQPI = .5618958354775629D0
C-----
      SQPI = 1/SQRT(PI)
C-----
      N6 = 0
      E = DPMPAR(2)
      E1 = 1D-20
      E1 = E1+E1
      E = MAX(E,E1)
      E2 = -DEPSLN(0)
      EPS = MAX(5D-7,10*DPMPAR(1))
      ELLRC = 1.0D99
      IF (P3 .EQ. 1.0D0) RETURN
      ELLRC = 0.0D0
      IF (P3 .EQ. 0.0D0) RETURN
      U(1) = 1.0D0/(SQ*S1)
      U(2) = 1.0D0/(SQ*S2)
      U(3) = 1.0D0/(SQ*S3)
      A(1) = ABS(H)*U(1)
      A(2) = ABS(HK)*U(2)
      A(3) = ABS(HL)*U(3)
      R1 = RMAX
      R0 = RMIN
      CALL FCN1(R1,A,U,P3,E,RA,T,F,R0,R1,IDEL)
      IF (ABS(F - P3) .GT. E8) GOTO 5
      ELLRC = R1
      RETURN

```

```

5  IF (F .LE. P3) RETURN
    CALL FCN1(R0,A,U,P3,E,RA,T,F,R0,R1,IDEL)
    IF (ABS(F - P3) .GT. E8) GOTO 10
    ELLRC = R0
    RETURN
10  IF (F .GE. P3) RETURN
    N6 = 0
15  ELLRC = 0.5D0*(R1 + R0)
    CALL FCN1(ELLRC,A,U,P3,E,RA,T,F,R0,R1,IDEL)
    N6 = N6 + 1
    IF (N6 .EQ. 40) RETURN
    IF (IDEL .NE. 0) GO TO 15
    IF (ABS(F - P3) .LT. 0.1D0*P3) GOTO 30
    GO TO 15
20  ELLRC = 0.5D0*(R1 + R0)
25  CALL FCN1(ELLRC,A,U,P3,E,RA,T,F,R0,R1,IDEL)
    N6 = N6 + 1
    IF (N6 .EQ. 40) RETURN
    IF (IDEL .NE. 0) GO TO 15
30  DO 40 J = 1,3
    T1 = 4*A(J)*RA(J)
    C = 1D0
    IF(T1 .GT. E2) GOTO 35
    C = 1D0 + EXP(-T1)
35  T2 = (A(J) - RA(J))
    RA(J) = EXP(-T2*T2)*C*U(J)
40  CONTINUE
    B1 = SQPI*(RA(1)*T(2)*T(3) + RA(2)*T(1)*T(3)
    *      + RA(3)*T(1)*T(2))
    IF (B1 .LE. 0.0D0) GO TO 15
    V1 = (F - P3)/B1
    ELLRC = ELLRC - V1
    IF ((ELLRC .LT. R0) .OR. (ELLRC .GT. R1)) GO TO 20
    IF (ABS(V1) .GE. 5.0D-5*ELLRC) GOTO 25
    IF (ABS(F - P3) .LT. 1.0D-3*P3) RETURN
    IF (ABS(V1) .LE. EPS*ELLRC) RETURN
    GO TO 25
END

```

```

SUBROUTINE FCN1(R,A,U,P3,E,RA,T,F,R0,R1,IDEL)
C-----
C   FCN1 USED IN ELLRC, IT GIVES THE PROBABILITY F OF A SHOT FALL-
C   ING UNDER A TRIVARIATE NORMAL DISTRIBUTION IN A CUBE CENTERED
C   AT (H,HK,HL) WITH SIDES OF LENGTH 2R. THE DISTRIBUTION HAS MEAN
C   (0,0,0) WITH STANDARD DEVIATIONS (S1,S2,S3). IF F .LT. DPMPAR(2),
C   IDEL = -1. IF F .GT. 1, IDEL = 1, OTHERWISE IDEL = 0.
C-----
      EXTERNAL      AERF
C-----
      DOUBLE PRECISION  AERF ,RA(1) ,A(1) ,T(1) ,U(1)
C-----
      DOUBLE PRECISION  E      ,F      ,P3      ,R      ,R0      ,R1      ,V
C-----
      F = 1D0
      IDEL = 0
      5 DO 10 J = 1,3
        RA(J) = R*U(J)
        T(J) = AERF(A(J),RA(J))/2
        F = F*T(J)
        IF (F .LT. E) GOTO 20
      10 CONTINUE
        V = F - P3
        IF (V .GT. 0D0) GOTO 15
        R0 = R
        RETURN
      15 R1 = R
        IF (F .GE. 1D0) GO TO 25
        RETURN
      20 IDEL = -1
        R0 = R
        RETURN
      25 IDEL = 1
        RETURN
      END

```

SUBROUTINE SUB3(P3,R3,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S  
+ ,PX,PXD,RL,PL,PLD,RH,PH,PHD,NN,KK)

C-----  
C SUB3 CALLS ELLCOV. ELLCOV COMPARED WITH P3. PX GIVES VALUE  
C OF ELLCOV. PXD GIVES PX - P3. PL = PX, PLD = PXD AND RL = R3  
C IF PXD .LT. 0. PH = PX, PHD = PXD AND RH = R3 IF PXD .GT. 0. NN  
C GIVES NUMBER OF ELLCOV CALLS. KK .NE. 0 MEANS THE ACCURACY  
C OF ELLCOV NEEDED IS OUT OF REACH.  
C-----

EXTERNAL	ELLCOV
DOUBLE PRECISION	ELLCOV

C-----  
C  
C DOUBLE PRECISION HX ,HY ,HZ ,PH ,PHD ,PL  
C DOUBLE PRECISION PLD ,PX ,PXD ,P3 ,RH ,RL  
C DOUBLE PRECISION R3 ,S ,SX ,SY ,SZ ,XK0  
C DOUBLE PRECISION XK2  
C-----

C  
KK = 0  
PX = ELLCOV(R3,HX,HY,HZ,SX,SY,SZ,XK0,XK2,S)  
IF (PX .GT. 0.0D0) NN = NN + 1  
PXD = PX - P3  
IF (PXD .GT. 0.0D0) GO TO 5  
RL = R3  
PL = PX  
IF (PXD .LT. PLD) KK = 1  
PLD = PXD  
RETURN  
5 RH = R3  
PH = PX  
IF (PXD .GT. PHD) KK = 1  
PHD = PXD  
RETURN  
END

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